## Position measurement | Incremental encoder interface

The KL5101 Bus Terminal processes differential signals according to the RS422/RS485 standard. This transmission type is particularly resistant to interference and is suitable for high transmission frequencies. The KL5111, KL5151 and KL5152 Bus Terminals have a single-ended input and are simple to wire up. The signal frequencies from less time-critical applications can be processed using these terminals.

All incremental encoder terminals use a quadrature decoder. Gate and latch inputs enable pre-processing in the Bus Terminal in order to be able to transfer positional values to the controller exactly upon an external event and thus support the referencing of a drive.

The KL5101 and KL5111 make a period duration measurement available with a resolution of 200 ns. Rotary speeds can thus be determined directly, since a calculation of the speed by means of position differences in the controller is in many cases not accurate enough due to jitter.

The KL5152 contains two encoders and provides a particularly inexpensive solution for a large number of channels if gate and latch functions are not needed.

The LEDs on the Bus Terminals indicate the states of the input signals for better diagnosis. 1-channel incremental encoder interface,16 bits, differential inputs, RS485

Technical data	KL5101   KS5101
Technology	incremental encoder interface (RS485)
Number of channels	1 incremental encoder + 1 input
Encoder connection	A, A (inv), B, B (inv), zero, zero (inv), difference signal (RS485); status input
	The KL5101 terminal is an interface for the direct connection of incremental encoders with difference signal (RS485) or with single inputs. A 16 bit counter with a quadrature decoder and a 16 bit latch for the zero pulse can be read, set or enabled. Interval measurement with a resolution of 200 ns is possible. The G2 input allows the counter to be halted
	(high = stop). The value is read with a rising edge at G1.
Power supply	(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %)
Current consum. pow.cont.	(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts)
Current consum. pow.cont. Current consumpt. K-bus	<pre>(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA</pre>
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage	(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) – (no power contacts) typ. 60 mA 5 V DC
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current	(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current Counter	<pre>(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A 16 bits, binary</pre>
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current Counter Limit frequency	<pre>(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A 16 bits, binary 4 million increments/s (with 4-fold evaluation)</pre>
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current Counter Limit frequency Quadrature decoder	<pre>(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A 16 bits, binary 4 million increments/s (with 4-fold evaluation) 1-, 2-, or 4-fold evaluation</pre>
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current Counter Limit frequency Quadrature decoder Zero-pulse latch	<pre>(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A 16 bits, binary 4 million increments/s (with 4-fold evaluation) 1-, 2-, or 4-fold evaluation 16 bits</pre>
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current Counter Limit frequency Quadrature decoder	<pre>(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A 16 bits, binary 4 million increments/s (with 4-fold evaluation) 1-, 2-, or 4-fold evaluation</pre>
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current Counter Limit frequency Quadrature decoder Zero-pulse latch	<pre>(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A 16 bits, binary 4 million increments/s (with 4-fold evaluation) 1-, 2-, or 4-fold evaluation 16 bits</pre>
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current Counter Limit frequency Quadrature decoder Zero-pulse latch Commands	<pre>(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A 16 bits, binary 4 million increments/s (with 4-fold evaluation) 1-, 2-, or 4-fold evaluation 16 bits</pre>
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current Counter Limit frequency Quadrature decoder Zero-pulse latch Commands Special features	<pre>(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A 16 bits, binary 4 million increments/s (with 4-fold evaluation) 1-, 2-, or 4-fold evaluation 16 bits read, set, enable -</pre>
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current Counter Limit frequency Quadrature decoder Zero-pulse latch Commands Special features Operating temperature	(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A 16 bits, binary 4 million increments/s (with 4-fold evaluation) 1-, 2-, or 4-fold evaluation 16 bits read, set, enable - -25+60 °C
Current consum. pow.cont. Current consumpt. K-bus Encoder operating voltage Encoder output current Counter Limit frequency Quadrature decoder Zero-pulse latch Commands Special features Operating temperature Approvals	(high = stop). The value is read with a rising edge at G1. 24 V DC (-15 %/+20 %) - (no power contacts) typ. 60 mA 5 V DC 0.5 A 16 bits, binary 4 million increments/s (with 4-fold evaluation) 1-, 2-, or 4-fold evaluation 16 bits read, set, enable - -25+60 °C CE, UL, Ex