

Ultra High-speed Laser Displacement Sensor CCD Style



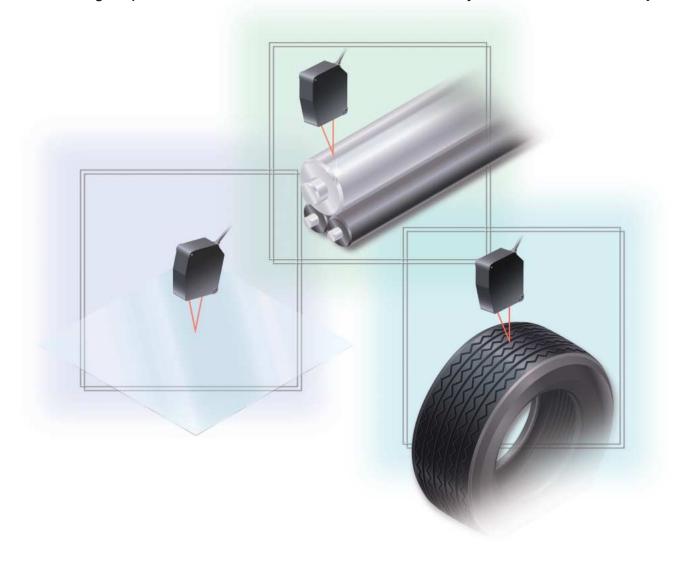
HL-C1 SERIES





## High speed of 100 µs

Ultra high-speed & stable measurement for a variety of measurement objects

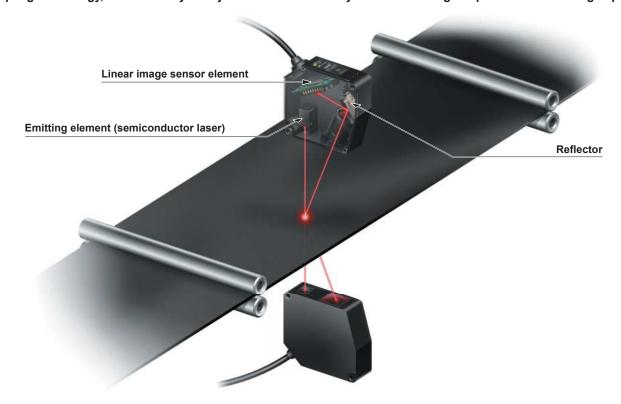


# Stable high-speed measurement is now available for a variety of measurement objects, through the combination of SUNX's unique 100 µs high-speed sampling optical system together with a linear image sensor.

Black rubber with a low reflected light intensity, objects with uneven surfaces, specular objects, such as wafers, and transparent objects, such as the glass used in liquid crystal displays.

SUNX has now integrated all the technologies required to enable stable and consistent measurement of these objects, which were previously considered as difficult objects to be measured.

Through the fusion of our unique newly developed optical system, linear image sensor method and high-speed sampling technology, a wide variety of objects can now be stably measured with great precision at ultra high speeds.



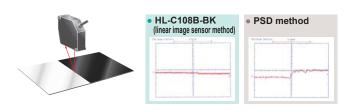
## 100 µs, fast sampling rate

Ultra high-speed sampling of 100 µs has now been achieved, thus enabling ultra high-speed measurement of rotating, vibrating and moving objects.

## High precision measurement is now possible, unaffected by the surface condition of the detected object

All deficiencies inherent in the conventional PSD sensing method have now been solved. Whereas the PSD method measures position information from the center of gravity of the total light quantity distribution of the light spots connected along each light element, the linear image sensor method measures the peak position values of the light spots themselves. This advancement now makes high-precision measurement possible, regardless of the surface condition of the object whether for metal hairline surface cracks or for non-reflective black rubber.

## Change in measurement data due to color difference (White Ceramic / Black Rubber)

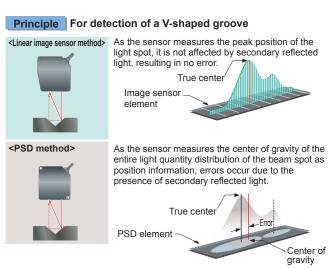


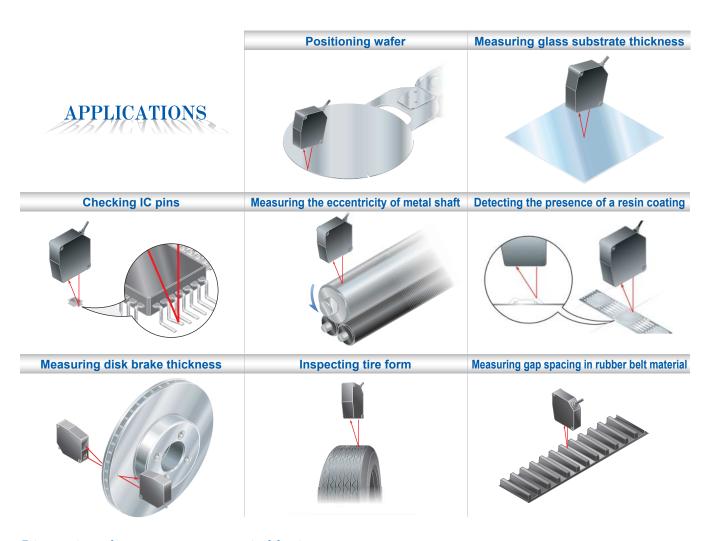
## Resolution of 1 $\mu$ m 0.039 mil, linearity of ±0.1 % F.S.

Now available with ultra-precise 1  $\mu m$  0.039 mil resolution measurement capability (HL-C105 $_{\square}$ ) and a linearity of ±0.1 % F.S. (for all models).

## FDA regulations conforming types are available

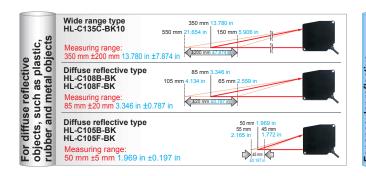
FDA regulations conforming types, most suitable for equipment used in the USA, are available.

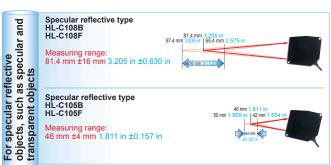




## 5 types to suit your measurement objects

5 types and 9 models are available depending on the measurement object and distance. In addition, a wide measuring range is possible to facilitate various measurement objects and installation conditions.





## The long and wide range

• Measures wide changes over long ranges

The long and wide range capabilities over 350 mm  $\pm 200$  mm 13.780 in  $\pm 7.874$  in allow large changes to be measured. Even if the object position changes, there is no need to change the sensor head settings or position.

 High speed and high precision even over long and wide ranges with an ultra-small head

High-speed and high-precision performance has been achieved in an ultra-small head of W26.6  $\times$  H82  $\times$  D87 mm W1.047  $\times$  H3.228  $\times$  D3.425 in with a high-speed sampling of 100  $\mu s$  at a resolution of 10  $\mu m$  0.394 mil, and a linearity of ±0.1 % F.S.

## Sensor head HL-C135C-BK10 Controller HL-C1C-M-WL

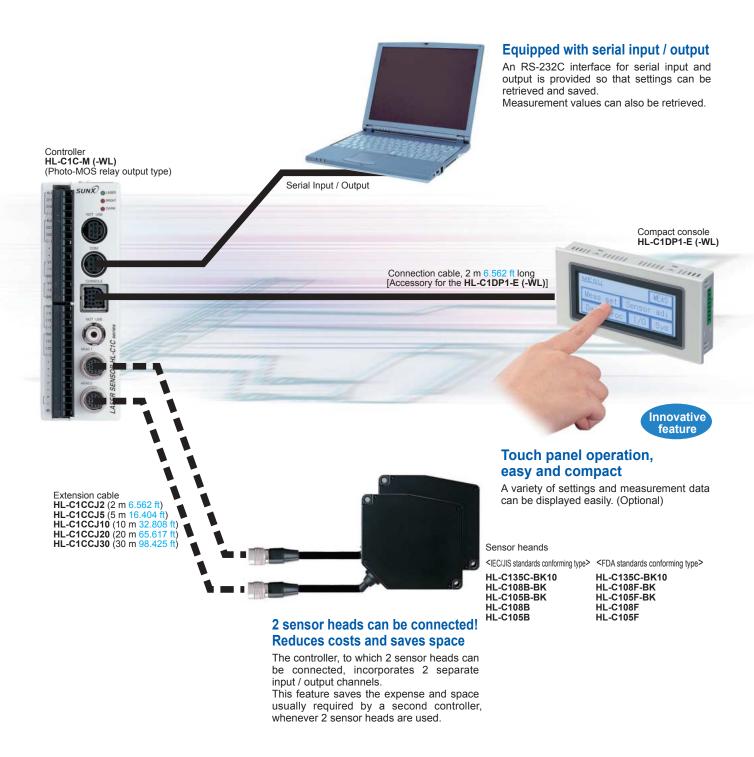


# Compact console with touch panel and thin, ultra-compact controller integrate high functionality to provide a comfortable operating environment!

The compact design significantly reduces the installation space required for the controller and console.

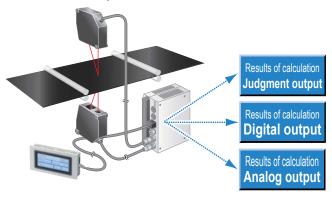
The controller allows multiple sensor head connections, reducing costs and saving space, yet incorporating a great variety of convenient functions.

The HL-C1 series integrates outstanding measurement performance and signal processing technology into a truly comfortable operating environment.



## Calculations can be performed when 2 sensor heads are used

The built-in calculation function allows measurement of gap and thicknesses without requiring a digital panel controller, thus saving further on costs and space.



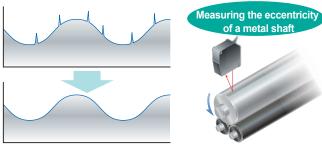
## **Enhanced functionality**

The **HL-C1** series incorporates a great number of useful functions, including hold function, calculation function, filter function and hysteresis-setting function, which facilitate convenient usage in a variety of diverse applications.

## Low-pass / High-pass Filter Functions

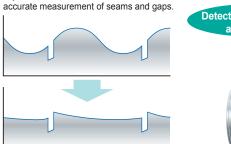
### <Low-pass filter function>

For example, if the surface condition of a metal object causes noise that interferes with accurate measurement, the use of the low-pass filter function will reduce the effects of noise and allow for stable measurement of displacement.



## <High-pass filter function>

When measuring seams and gaps in objects that undergo large displacement changes due to vibration or tilting, such as measuring the eccentricity of a rotating object, this function will minimize the effects of these undulations and enable





## Waterproof sensor head construction, compliant with IP67 rated protection

The **HL-C1** series can withstand water splashes.



Note: Accurate measurement cannot be performed if water is present on the sensing window of the sensor head itself.

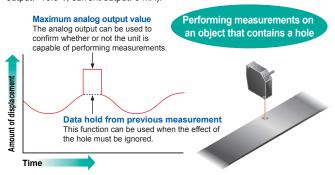
## Compact controller and front connection reduce setup space

The ultra-compact controller HL-C1C-M with dimensions of W40 × H120 × D74 mm W1.575 × H4.724 × D2.913 in requires much less space for installation. Tight installation is also possible. Furthermore, the cables can be connected directly or to a removable terminal block, so that all connections come from the same direction in order to further save space.



## **Analog Output Switching Function During Alarm Output**

During measurement, if the unit becomes incapable of performing measurements due to excessive or insufficient incident light intensity (during alarm output), this function allows the analog output to be switched to either hold the data obtained just previously, or to output a fixed value. If the fixed value is selected, one of two options can be chosen for the analog output, during alarm output: the output of the maximum value (voltage output: +10.9 V, current output: 29.5 mA) or the output of the minimum value (voltage output: -10.9 V, current output: 0 mA).



## **Hold Functions**

The **HL-C1** series incorporates 4 hold modes.

The TIE-OT Series incorporates 4 hold modes.			
NORM (no hold) This mode outputs the amount of displacement from the measurement ce distance in real time. This mode is utilized for general-purpose operation.			
P-P	This mode holds the output at the difference between the maximum and minimum measured values. This mode is utilized for vibration or eccentricity measurements.		
PEAK	This mode holds the output at the maximum measured value.		
VALLEY	This mode holds the output at the minimum measured value.		

## Easy maintenance with sensor head compatibility

Maintainability has been significantly improved. Compatibility has been achieved through the incorporation of correction data into the sensor heads themselves. This sensor series no longer needs the amount of maintenance usually required for conventional displacement sensors of its class.

## HL-C1

## ORDER GUIDE

## **Sensor heads**

Ту	ре	Appearance	Measurement center distance	Resolution (Note 1, 2)	Beam diameter	Model No.	Applicable controller	Applicable console	Conforming standards / regulations
e type	Wide range	**	350 mm 13.780 in (Measuring range ±200 mm ±7.874 in)	10 µm 0.394 mil	400 × 200 μm 15.748 × 7.874 mil approx.	HL-C135C-BK10	HL-C1C-M-WL	HL-C1DP1-E-WL	IEC / JIS / FDA
Diffuse reflective type	General purpose			2 µm	100 × 140 µm 3.937 × 5.512 mil	HL-C108B-BK			IEC / JIS
use re			85 mm 3.346 in (Measuring range ±20 mm ±0.787 in)	0.079 mil	approx.	HL-C108F-BK			FDA / IEC / JIS
Diff	precision		50 mm 1.969 in (Measuring range ±5 mm ±0.197 in)	1 µm 0.039 mil	70 × 120 μm 2.756 × 4.724 mil approx.	HL-C105B-BK			IEC / JIS
	High pr					HL-C105F-BK			FDA / IEC / JIS
/be	purpose	as and an analysis of the state	81.4 mm 3.205 in (Measuring range ±16 mm ±0.630 in)	2 µm 0.079 mil	100 × 140 μm 3.937 × 5.512 mil approx.	HL-C108B	HL-C1C-M	HL-C1DP1-E	IEC / JIS
flective t	General					HL-C108F			FDA / IEC / JIS
Specular reflective type	precision			1 μm	70 × 120 μm	HL-C105B			IEC / JIS
Spe	High pr	46 mm 1.811 in (Measuring range ±4 mm ±0.157 in)		0.039 mil	2.756 × 4.724 mil approx.	HL-C105F			FDA / IEC / JIS

Notes: 1) These values were obtained by converting P-P values into a distance. The P-P values indicate the distribution of measured values throughout the

## **Controllers**

Туре	Appearance	Model No.	Judgment outputs	
Standard		HL-C1C-M	Photo-MOS relay	
For <b>HL-C135C-BK10</b>		HL-C1C-M-WL		

## **Compact consoles**

Туре	Appearance	Model No.
Standard		HL-C1DP1-E
For <b>HL-C1C-M-WL</b>		HL-C1DP1-E-WL

measurement center distance.

2) These values were obtained with an average number of samples: 256, when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types).

## **ORDER GUIDE**

## Sensor head extension cable

Appearance	Model No.	Description	
	HL-C1CCJ2	Length: 2 m 6.562 ft, Net weight: 160 g approx.	
	HL-C1CCJ5	Length: 5 m 16.404 ft, Net weight: 350 g approx.	Cabtyre cable with connector on both ends
	HL-C1CCJ10	Length: 10 m 32.808 ft, Net weight: 700 g approx.	Cable outer diameter: ø7 mm ø0.276 in Connector outer diameter: ø14.7 mm
	HL-C1CCJ20	Length: 20 m 65.617 ft, Net weight: 1,400 g approx.	ø0.579 in max.
	HL-C1CCJ30	Length: 30 m 98.425 ft, Net weight: 2,000 g approx.	

## Intelligent monitor

Appearance	Model No.	Description
Intelligent Monitor HI-CLAIM Advanced Massier  According to the control of the co	HL-C1AiM	Enables the waveform display of each measurement condition setting and of measurement values as well as monitoring of measurement data and received light intensity data.  1pc. of COM port connection cable manufactured by Matsushita Electric Works, Ltd. is attached.

## SPECIFICATIONS

## Sensor heads

Туре				Diffuse reflective type		
		Туре	Wide range	General purpose	High precision	
	Model No.	IEC / JIS standards conforming type	III 04250 BK40	HL-C108B-BK	HL-C105B-BK	
Item	Mode 1	FDA regulations conforming type	HL-C135C-BK10	HL-C108F-BK	HL-C105F-BK	
Mea	surement of	center distance	350 mm 13.780 in	85 mm 3.346 in	50 mm 1.969 in	
Mea	suring rang	ge	±200 mm ±7.874 in	±20 mm ±0.787 in	±5 mm ±0.197 in	
Res	olution (No	te 2, 3)	10 μm 0.394 mil	2 μm 0.079 mil	1 µm 0.039 mil	
Line	arity (Note	4)		±0.1 % F.S.		
Tem	perature cl	haracteristics		0.02 % F.S./°C		
Lase	er emission	indicator	Green LED (lights of	up during laser emission or immediately bef	ore laser emission)	
Mea	suring rang	ge indicator	Yellow LED (blinks within the m	easuring range and lights up when near the	e measurement center distance)	
	Pollution (	degree		3 (Industrial environment)		
nce	Protection	า		IP67 (IEC) (excluding the connector)		
istai	Ambient t	emperature	0 to +45 °C +32 to +113 °F (No dew condensation), Storage: -20 to +70 °C -4 to +158 °F			
res	Ambient h	numidity	35 to 85 % RH, Storage: 35 to 85 % RH			
ntal	Ambient i	lluminance	Incandescent light: 3,000 tx at the light-receiving face			
Environmental resistance	Voltage w	vithstandability	500 V AC for one min. between the exclusive controller power input part and the sensor head enclosure			
iron	Insulation resistance $20 \text{ M}\Omega$ , or more, with 500 V DC megger between the exclusive controller power input part and the sensor head enclosed in the sensor head enclos		out part and the sensor head enclosure			
En	Vibration resistance 10 to 55 Hz (period: 1 min.) frequency, 1.5 mm 0.059 in amplitude in X,Y and Z directions for two hours each		d Z directions for two hours each			
	Shock res	sistance	196 m/s² accelerat	ion (20 G approx.) in X,Y and Z directions for	or three times each	
Emit	Emitting element		Red semiconductor laser, Class 3B (Class III b for FDA regulations) (Max. output: 10 mW, Peak emission wavelength: 658 nm 0.026 mil)	Red semiconductor laser, Class 2 (Class I (IEC / JIS standards conforming type: IEC FDA / IEC / JIS) (Max. output: 1 mW, Peal	/ JIS, FDA regulations conforming type:	
Bear	Beam diameter (Note 5)		400 × 200 μm 15.748 × 7.874 mil approx.	100 × 140 μm 3.937 × 5.512 mil approx.	70 × 120 μm 2.756 × 4.724 mil approx.	
Receiving element		nent	Linear image sensor			
Enclosure earthing		ning	Floating			
Material			Enclosure: Die-cast	Enclosure: Die-cast aluminum, Case cover: Die-cast aluminum, Front cover: Glass		
Cable			Ca	btyre cable, 0.5 m 1.640 ft long with connec	ctor	
Cable extension		extension Extension up to total 30 m 98.425 ft is possible, with optional cable.		tional cable.		
Weig	ght			Net weight: 300 g approx.		
Acce	essory		English warning label: 1 set [The FDA regulations co	onforming type includes a set of both the IEC label (wi	itten in English) and JIS label (written in Japanese)].	

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage 24 V DC, ambient temperature +20 °C +68 °F, sampling rate 100 µs, average number of samples: 256 (HL-C135C-BK10: 512), object measured at measurement center distance is made of white ceramic (an aluminum vapor deposition surface reflection mirror was used with specular reflective type). Linearity also depends upon the characteristics of the object being measured.

- 2) These values were obtained by converting P-P values into a distance. The P-P values indicate the distribution of measured values throughout the measurement center distance.
- 3) These values were obtained with an average number of samples: 256 (HL-C135C-BK10: 512), when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types).
- 4) This value indicates the range of errors for an ideal linear displacement output, when using an object made of our company's standard white ceramic for measurement (an
- aluminum vapor deposition surface reflection mirror was used with specular reflective types). This value may fluctuate depending on the characteristics of the object measured.

  5) These values were defined by using 1/e² (13.5 %) of the center light intensity. If there is a slight leakage of light outside the normal spot diameter and if the periphery surrounding the sensing point has a higher reflectivity than the sensing point itself, then the results may be affected.

## HL-C1

## SPECIFICATIONS

### **Sensor heads**

	Typo	Specular re	flective type		
	Туре	General purpose	High precision		
`	IEC / JIS standards conforming type  FDA regulations	HL-C108B	HL-C105B		
Item	FDA regulations conforming type	HL-C108F	HL-C105F		
Mea	surement center distance	81.4 mm 3.205 in	46 mm 1.811 in		
Mea	suring range	±16 mm ±0.630 in	±4 mm ±0.157 in		
Res	olution (Note 2, 3)	2 μm 0.079 mil	1 μm 0.039 mil		
Line	arity (Note 4)	±0.1 %	6 F.S.		
Tem	perature characteristics	0.02 %	F.S./°C		
Lase	er emission indicator	Green LED (lights up during laser emissi	on or immediately before laser emission)		
Mea	suring range indicator	Yellow LED (blinks within the measuring range and lig	ghts up when near the measurement center distance)		
	Pollution degree	3 (Industrial e	environment)		
ρ	Protection	IP67 (IEC) (excluding the connector)			
stanc	Ambient temperature	0 to +45 °C +32 to +113 °F (No dew condens	eation), Storage: -20 to +70 °C -4 to +158 °F		
resis	Ambient humidity	35 to 85 % RH, Storage: 35 to 85 % RH			
ental	Ambient illuminance	Incandescent light: 3,000 & at the light-receiving face			
onme	Voltage withstandability	500 V AC for one min. between the exclusive controller power input part and the sensor head enclosure			
Environmental resistance	Insulation resistance	20 M $\Omega$ , or more, with 500 V DC megger between the exclusive	ve controller power input part and the sensor head enclosure		
ш	Vibration resistance	10 to 55 Hz (period: 1 min.) frequency, 1.5 mm 0.059 i	n amplitude in X,Y and Z directions for two hours each		
	Shock resistance	196 m/s² acceleration (20 G approx.) in $\lambda$	X,Y and Z directions for three times each		
Emit	ting element	Red semiconductor laser, Class 2 (Class II for FDA regulati FDA regulations conforming type: FDA / IEC / JIS) (Max. o.			
Bear	m diameter (Note 5)	100 × 140 μm 3.937 × 5.512 mil approx.	$70 \times 120 \ \mu m \ 2.756 \times 4.724 \ mil \ approx.$		
Rec	eiving element	Linear image sensor			
Enclosure earthing		Floating			
Material		Enclosure: Die-cast aluminum, Case cover: Die-cast aluminum, Front cover: Glass			
Cab	le	Cabtyre cable, 0.5 m 1.640 ft long with connector			
Cab	le extension	Extension up to total 30 m 98.425	ft is possible, with optional cable.		
Wei	ght	Net weight: 3	00 g approx.		
Acce	essory	English warning label: 1 set [The FDA regulations conforming type includes a s	et of both the IEC label (written in English) and JIS label (written in Japanese)].		

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage 24 V DC, ambient temperature +20 °C +68 °F, sampling rate 100 µs, average number of samples: 256, object measured at measurement center distance is made of white ceramic (an aluminum vapor deposition surface reflection mirror was used with specular reflective type). Linearity also depends upon the characteristics of the object being measured.

- 2) These values were obtained by converting P-P values into a distance. The P-P values indicate the distribution of measured values throughout the measurement center distance.
- 3) These values were obtained with an average number of samples: 256, when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types).
- 4) This value indicates the range of errors for an ideal linear displacement output, when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types). This value may fluctuate depending on the characteristics of the object measured.
- 5) These values were defined by using 1/e² (13.5 %) of the center light intensity. If there is a slight leakage of light outside the normal spot diameter and if the periphery surrounding the sensing point has a higher reflectivity than the sensing point itself, then the results may be affected.

## **SPECIFICATIONS**

## **Controllers**

con	trollers				
	Type	Photo-MOS	relay output		
	1,700	Standard	For <b>HL-C135C-BK10</b>		
tem		HL-C1C-M	HL-C1C-M-WL		
	ection sensor heads	Maximum 2 sensor heads			
	ly voltage	24 V DC ±10 % including ripple 0.5 V (P-P)			
	ent consumption	When 1 sensor is connected: 430 mA approx., When 2 sensors are connected: 550 mA approx.			
	oling rate		μs / 255 μs / 332 μs / 498 μs / 1,000 μs		
em	perature characteristics		5 F.S./°C		
Analog output	Voltage	Output voltage: $\pm 5$ V/F.S. [default setting when diffuse reflective mode is selected (Note 2)] Output range: $-10.9$ to $+10.9$ V Output current: Max. 2 mA, Output impedance: $50 \Omega$			
Analog	Current (Note 3)	Output current: 4 to 20 mA/F.S. [default setting v Output range: 0 to 29.5 mA (maximum of 25 mA Load impedance: 250 Ω or less	when diffuse reflective mode is selected (Note 4)] at max. load impedance)		
Alarr	n output	Photo-MOS relay  • Maximum load current: 50 mA  • Applied voltage: 30 V DC or less  • ON impedance: 35 Ω or less  • Operation time: Max. 2 ms	(between alarm output and COM)		
	Output operation	Opened when the amount of li	ght is excessive or insufficient.		
	Short-circuit protection	Incorp	orated		
Judg O1,	ment outputs O2)	Photo-MOS relay  • Maximum load current: 50 mA  • Applied voltage: 30 V DC or less (between judgment output and COM)  • ON impedance: 35 Ω or less  • Operation time: Max. 2 ms			
	Utilization category	DC-12 c	or DC-13		
	Output operation	Opened or closed when the threshold value is reached. Determined based on judgment output mode selection. (The threshold value varies with the hysteresis setting.			
	Short-circuit protection	Incorporated			
Seria	l input / output	RS-2	232C		
Timing input (Laser emission)		Laser emission stops or continues when voltage (using input voltage: 12 to 24 V DC, maximum input voltage: 30 V DC) is input or there is an open circuit: determined based on input mode selection.			
Rem	ote interlock input		Laser emission stops when open circuit		
'ero	set ON input	Zero set: ON when voltage (using input voltage: 12 to 24 V DC, maximum input voltage: 30 V DC) is input			
ero	set OFF input	Zero set: OFF when voltage (using input voltage: 12 to 24 V DC, maximum input voltage: 30 V DC) is input			
ors	Laser emission	Green LED (lights up during laser emission from sensor hea	ad 1 or sensor head 2, or immediately before laser emission)		
Indicators	BRIGHT	Red LED (lights up upon disabled measureme	nt due to excessive light at sensor head 1 or 2)		
Ĕ	DARK	Red LED (lights up upon disabled measureme	nt due to insufficient light at sensor head 1 or 2)		
	ng / Data display	Compact con-	sole (optional)		
(Note 5)	Shift	±20.0000 mm ±0.787 in	±200.0000 mm ±7.874 in		
(Not	Span	0.9000 t	o 1.1000		
vera	ge number of samples (Note 5)	OFF, 2 to 32,768	3 times (16 steps)		
Digital filters (Note 5)		High pass: OFF, 10 to 2,000 Hz (9 steps)	, Low pass: OFF, 10 to 2,000 Hz (9 steps)		
Calculation functions (Note 5)		$L\pm$ KA, $L\pm$ KB, $L\pm$ K (A $\pm$ B) A, B: Sensor head 1, Sensor head 2 measurement values, $L=\pm999.9999$ , K = 0.0001 to 99.9999			
	functions (Note 5)		L / P-P / PEAK / VALLEY		
Pollution degree		3 (Industrial environment)			
SISTS	Ambient temperature		sation), Storage: –20 to +70 °C –4 to +158 °F		
a re	Ambient humidity	·	rage: 35 to 85 % RH		
ent	Voltage withstandability		power input part and enclosure		
Environmental resistance	Insulation resistance		between power input part and enclosure		
nvir	Vibration resistance	in amplitude in X,Y and Z directions for 30 min. each			
	Shock resistance		and Z directions for 3 times each		
	e length		, Signal line: Less than 30 m 98.425 ft		
Veig		Net weight: 3	300 g approx.		
	ssory		Key: 2 pcs.		

- Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage 24 V DC, ambient temperature +20 °C +68 °F, sampling rate 100 µs, average number of samples: 256 (HL-C1C-M-WL: 512), and measurement center distance.

  2) If specular reflective mode is selected, then the default setting is ±4 V/F.S.

  - 3) The maximum analog output current will vary with load impedance.
  - 4) If specular reflective mode is selected, then the default setting is 5.6 to 18.4 mA/F.S.
  - 5) These values can be set using the command input from external equipment via the compact console and RS-232C interface.

## HL-C1

## **SPECIFICATIONS**

## **Compact consoles**

		Туре	Standard	For <b>HL-C1C-M-WL</b>		
Item	Item Model No.		HL-C1DP1-E	HL-C1DP1-E-WL		
Supp	oly voltage		24 V DC ±10 % includ	ding ripple 0.5 V (P-P)		
Current consumption		ption	200 mA	or less		
	Display ele	ment	STN monoc	hrome LCD		
Display	Back light		White	LED		
Disp	Display rar	ige	-999.9999 t	to 999.9999		
	Language		Eng	lish		
Touch	Operation	force	0.5 N (	or less		
Tor	Lifetime		1,000,000 times or more (Note 1)			
Environmental resistance	Environme	nt resistance	IP65 (at initial status) (Note 2)  Dust prevention and drip-proof at the front panel (waterproof packing is used at the contact surface to board)			
esist	Ambient te	mperature	0 to +50 °C +32 to +122 °F (No dew condensation or icing allowed), Storage: -20 to +60 °C -4 to +140 °F			
ıtal re	Ambient hu	ımidity	20 to 85 % RH, Storage: 10 to 85 % RH			
ımer	Electrostatic	noise resistance	5,000 V or more (panel surface)			
viror	Vibration re	esistance	10 to 55 Hz frequency, 0.75 mm 0.030 in ampli	itude in X, Y, and Z directions for 10 min. each		
핃	Shock resi	stance	98 m/s² or more acceleration (10G approx.) in X, Y, and Z directions for four times each			
Material		Case: PPE, Front protective sheet: Polyester				
Weig	ght 230 g approx.		арргох.			
Acce	essory		Connection cable for connecting the controller	to the console: 1 pc., Mounting bracket: 1 set		

Notes: 1) This value indicates the average lifetime of the unit when used under a normal temperature of +25 °C +77 °F.

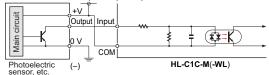
2) When reinstalling the console, replace the water proof packing. (Matsushita Electric Works, Ltd., Part No: AIGT181, 10 packs included)

## I/O CIRCUIT AND WIRING DIAGRAMS

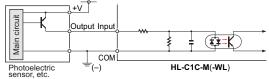
## HL-C1C-M(-WL) Controller

## Input circuit diagram

### Connection example 1 (NPN)

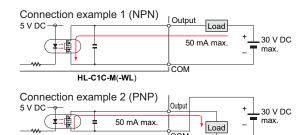


## Connection example 2 (PNP)



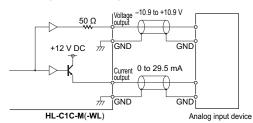
## **Output circuit diagram**

### Alarm output, Judgment output



## **Analog output diagram**

HL-C1C-M(-WL)



Notes: 1) Do not short-circuit analog output terminals or apply vottage to them.

2) Use shielded wires for analog outputs.

## **Terminal arrangement**

Input to	erminal
TM1   111   112   COM   TM2   121   122   COM	

Symbol	Description	
TM1 (Note 1)	Timing input (sensor head 1) (Note 1)	
I11 Zero set ON input (sensor head 1)		
l12	Zero set OFF input (sensor head 1)	
COM	Input common	
TM2 (Note 2)	Timing input (sensor head 2) (Note 2)	
I21	Zero set ON input (sensor head 2)	
122	Zero set OFF input (sensor head 2)	
COM	Input common	
•	Not used	
+	24 V DC input for power supply	
_	Power supply ground	
<b>4</b>	Function ground	
	TM1 (Note 1) 111 112 COM TM2 (Note 2) 121 122 COM	

## **Output terminals**

Output	 	
AL1 O11 O12 LCOM AL2 O21 O22 LCOM		
V1		

Symbol	Description	
AL1	Alarm output (sensor head 1)	
O11	Judgment output 1 (sensor head 1)	
O12	Judgment output 2 (sensor head 1)	
COM	Output common	
AL2	Alarm output (sensor head 2)	
O21	Judgment output 1 (sensor head 2)	
O22	Judgment output 2 (sensor head 2)	
COM	Output common	
•	Not used	
•	Not used	
V1	Analog voltage output (sensor head 1)	
l1	Analog current output (sensor head 1)	
GND	Analog output ground	
V2	Analog voltage output (sensor head 2)	
12	Analog current output (sensor head 2)	
GND	Analog output ground	

Notes: 1) In the case of HL-C1C-M-WL, "IL1: Remote interlock input (sensor head 1)"

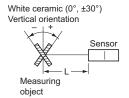
- 2) In the case of **HL-C1C-M-WL**, "IL2: Remote interlock input (sensor head 2)"
- 3) Terminals marked with "•" are not used. Some are connected to internal circuitry and cannot be used as relay terminals in wiring, etc.

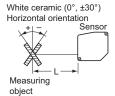
## SENSING CHARACTERISTICS (TYPICAL)

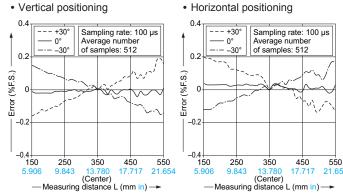
## HL-C135C-BK10

## Diffuse reflective type

## Correlation between measuring distance and error characteristics



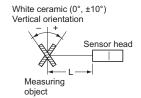


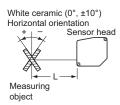


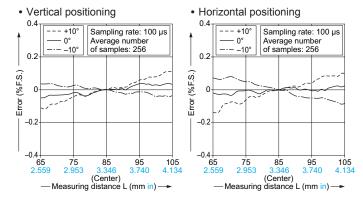
## SENSING CHARACTERISTICS (TYPICAL)

## HL-C108□-BK Diffuse reflective type

### Correlation between measuring distance and error characteristics

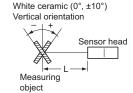


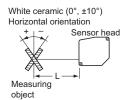




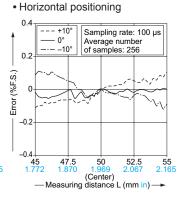
## HL-C105□-BK

### Correlation between measuring distance and error characteristics





### Vertical positioning +10 Sampling rate: 100 µs Average number -10 0.2 Error (%F.S.) -0.2 \_0 4 45 1.772 47.5 1.870 50 52.5 55 2.165 (Center) Measuring distance L (mm in)

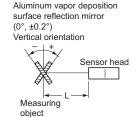


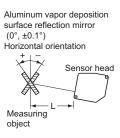
Diffuse reflective type

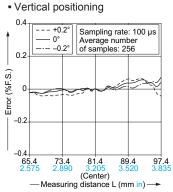
## HL-C108B HL-C108F

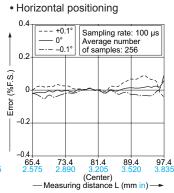
## Specular reflective type

## Correlation between measuring distance and error characteristics









## HL-C105B HL-C105F

object

## Specular reflective type

### Correlation between measuring distance and error characteristics

surface reflection mirror (0°, ±0.5°)
Vertical orientation

Sensor head

Measuring

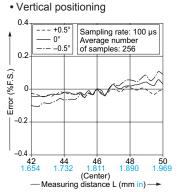
Aluminum vapor deposition

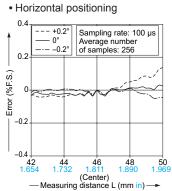
surface reflection mirror (0°, ±0.2°)
Horizontal orientation

Sensor head

Measuring
object

Aluminum vapor deposition





 This catalog is a guide to select a suitable product. Be sure to read instruction manual attached to the product prior to its use.



• Never use this product as a sensing device for personnel protection.

 In case of using sensing devices for personnel protection, use products which meet laws and standards, such as OSHA, ANSI or IEC etc., for personnel protection applicable in each region or country.

## HL-C108 | HL-C105 |

- This product is classified as a Class 2 Laser Product in IEC / JIS standards and a Class II Laser Product in FDA regulations. Do not look at the laser beam directly or through optical system such as a lens.
- The following label is attached to the product. Handle the product according to the instruction given on the warning label.



(The English warning label based on FDA regulations is pasted on the FDA regulations conforming type.

(The English warning label is packed with the sensor)

HL-C135C-BK10

- This product is classified as a Class 3B Laser Product in IEC / JIS standards Class IIIb. Never look at or touch the direct laser beam and its reflection.
- The following label is attached to the product. Handle the product according to the instruction given on the warning label.



(The English warning label based on FDA regulations is pasted on the FDA regulations conforming type.

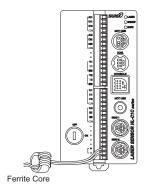
(The English warning label is packed with the sensor)

## To comply with the European EMC Directive (HL-C1C-M-WL)

 To comply with the European EMC Directive, install a ferrite core on wires to the terminal block as shown below.

## Recommended ferrite core:

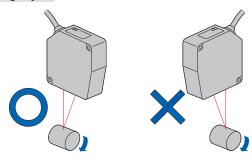
E04RC281613 manufactured by Seiwa Electric Mfg. Co., Ltd or equivalent



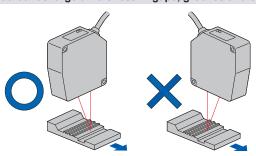
## Sensor head mounting direction

• To obtain the greatest precision, the sensor head should be oriented facing the direction of movement of the object's surface, as shown in the figure below.

### Rotating object



## Object that has large differences in gaps, grooves and colors



## Safety standards for laser beam products

A laser beam can harm human being's eyes, skin, etc., because of its high energy density. IEC and JIS have classified laser products according to the degree of hazard and the stipulated safety requirements.
 HL-C108

 and HL-C105

 Classified as Class 2 laser products
 HL-C135C-BK10: Classified as a Class 3B laser products

## Classification by IEC 60825-1: 2001

·		
Classification	Description	
Class 1	Lasers that are safe under reasonably foreseeable conditions of operation, including the use of optical instruments for intrabeam viewing.	
Class 1M	Lasers emitting in the wavelength range from 302.5 nm to 4,000 nm which are safe under reasonably foreseeable conditions of operation, but may be hazardous if the user employs optics within the beam.	
Class 2	Lasers that emit visible radiation in the wavelength range from 400 nm to 700 nm where eye protection is normally afforded by aversion responses, including the blink reflex.  This reaction may be expected to provide adequate protection under reasonably foreseeable conditions of operation including the use of optical instruments for intrabeam viewing.	
Class 2M	Lasers that emit visible radiation in the wavelength range from 400 nm to 700 nm where eye protection is normally afforded by aversion responses, including the blink reflex. However, viewing of the output may be more hazardous if the user employs optics within the beam.	
Class 3R	Lasers that emit in the wavelength range from 302.5 nm to 10 <sup>6</sup> nm where direct intrabeam viewing is potentially hazardous but the risk is lower than for Class 3B lasers, and fewer manufacturing requirements and control measures for the user apply than for Class 3B lasers.	
Class 3B	Lasers that are normally hazardous when direct intrabeam exposure occurs (i.e. within the NOHD). Viewing diffuse reflections is normally safe.	
Class 4	Lasers that are also capable of producing hazardous diffuse reflections. They may cause skin injuries and could also constitute a fire hazard.	

## Safe use of laser products

 For the purpose of preventing users from suffering injuries by laser products, IEC 60825-1: 2001 (JIS C 6802: 2005) (Safety of laser products).
 Kindly check the standards before use.

## Summary of user precautions IEC 60825-1: 2001 (JIS C 6802: 2005)

\* Quoted from Safety of laser products, Annex Table D. 3

Deguiremente	Classification						
Requirements subclause	Class 1	Class 1M	Class 2	Class 2M	Class 3R	Class 3B	Class 4
Laser safety officer	Not required but recommended for applications that involve direct viewing of the laser beam  Not required for visible emission Required for non-visible emission					Required	
Remote interlock		N	ot require	ed		Connect or door o	to room circuits
Key control		N	ot require	ed		Remove when no	
Beam attenuator		N	ot require	ed		When in us	se prevents t exposure
Emission indicator device	indicates laser is energized for non-visible wavelengths			Indicates laser is energized			
Warning signs	Not required			Follow pro	ecautions ng signs		
Beam path	Not required Class 1M (Note 1) as for Class 3B required Class 3B required Class 3B			at end			
Specular reflection	No requirements	Class 1M (Note 1) as for Class 3B	No requirements	Class 2M (Note 2) as for Class 3B	Prevent unintentional reflections		
Eye protection	Required if engineering and administrative procedures not practicable and MPE exceeded						
Protective clothing	No requirements Sometimes required requirements						
Training	No Class 1M (Note 1) as for requirements (Class 3R) Required for all operator class 3R Required for all operator and maintenance personnel						

Notes: 1) Class 1M laser products that failed condition 1 of table 10.

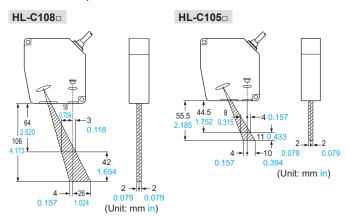
Not required for Class 1M laser products that failed condition 2 of table 10.

 Class 2M laser products that failed condition 1 of table 10.
 Not required for Class 2M laser products that failed condition 2 of table 10.

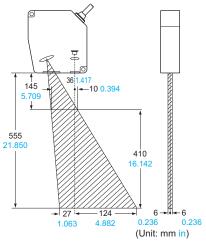
Remarks: This table is intended to provide a convenient summary of precautions. See text of this standard for complete precautions.

### **Mutual interference**

• When installing 2 or more sensor heads side by side, mutual interference will not occur if the laser spots from other sensor heads do not fall within the shaded areas of the sensor head in the figure below. Multiple sensor heads must be installed in a manner such that laser spots from other sensor heads will be prevented from falling within these shaded areas. When two sensor heads are connected to a controller and used, the measures described below are not required since the mutual interference prevention function can be used.



## HL-C135C-BK10



## **Functional description**

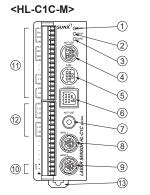
## Sensor head

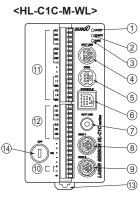


	Description	Function
1	Laser emission indicator (Green LED)	Lights up during laser emission or immediately before laser emission.
2	Measuring range indicator (Yellow LED)	Blinks within the measuring range and lights up when near the measurement center distance.
3	Warning label	Shows the laser emission position.

## **Functional description**

## Controller





	Description	Function
1	Laser emission indicator (Green LED)	Lights up during laser emission from sensor head 1 or sensor head 2, or immediately before laser emission.
2	BRIGHT indicator (Red LED)	Lights up upon disabled measurement due to excessive light at sensor head 1 or 2.
3	DARK indicator (Red LED)	Lights up upon disabled measurement due to insufficient light at sensor head 1 or 2.
4		Cannot be used. This port is for adjustment at the factory before shipping.
(5)	COM. port	Used for RS-232C communications with a personal computer.
6	Connector for compact console	This enables measurement values to be displayed using the compact console and connection of the compact console exclusive connection cable when setting each setting.
7		Cannot be used. This port is for adjustment at the factory before shipping.
8	Sensor head 1 connector	The controller operates the sensor head connected to this connector as sensor head 1.
9	Sensor head 2 connector	The controller operates the sensor head connected to this connector as sensor head 2.
10	Power supply terminal	Supplies 24 V DC. There are power supply terminals on input terminal block.
(1)	External output terminal	<del></del>
(12)	External input terminal	<del></del>
13	DIN rail mounting hook	Can be mounted on a 35 mm 1.378 in width DIN rail quickly.
(14)	Key switch	Turning on the key switch starts up the controller. Please take out the key when it is not being used.

## **Functions**

Function	Details	
Data buffering function	<ul> <li>It is possible to accumulate data up to 48,000 data into a controller temporarily in order to capture measurement data into a PC. All the accumulated data can be captured into the PC with HL-C1AiM. Used for reading and storing all data including the verification of measurement data when introduced as well as all post-measurement data.</li> </ul>	
Hold function	NORM. (no hold): Outputs the amount of displacement from the measurement center distance in real time. Ordinarily, this mode is used. P-P: This mode holds and outputs the difference between the maximum value and the minimum value. It is used for vibration measurements or eccentricity. PEAK: Holds and outputs the maximum measurement value. VALLEY: Holds and outputs the minimum measurement value.	

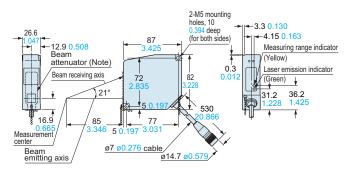
Function	Details	
Zero set function	<ul> <li>The measurement value and analog output at the timing of zero setting are forcibly reset to zero. Use this function to reset the measurement value of the reference object to zero and measure the displacement amount or make a judgment of the upper or lower limit.</li> </ul>	
Timing function (excluding HL-C1C-M-WL)	<ul> <li>The judgment outputs (O1 and O2) immediately before the mode selection, measurement value and analog output are held in the timing input mode. Laser emission can be halted or continued according to a setting. Add the input in other than the measurement or judgment state to eliminate unnecessary output changes or laser radiation.</li> </ul>	
Remote interlock function [HL-C1C-M-WL only]	<ul> <li>This function stops laser radiation. Turning on the remote interlock input maintains the judgment output and then either holds values measurement values or analog outputs to the values just obtained or outputs the fixed values.</li> </ul>	
Display hold function	<ul> <li>Only the measurement value displayed on the compact console is held. Use this function to read a momentary measurement value.</li> </ul>	
Switching functions for sampling rate	• In cases where objects with a low reflected light amount, such as black rubber, are measured, stable measurements can be taken by extending the sampling rate and enabling a sufficient amount of light to be picked up by the sensor. If the sampling rate is short and not enough light can be picked up, the sensor enters the alarm state, so switch the sampling rate to a longer duration setting. The sampling rate can be switched among 7 different rates. (100 µs / 144 µs / 200 µs / 255 µs / 332 µs / 498 µs / 1,000 µs)	
Calculation function	This function enables the unit to perform the following calculations: <calculation formulas="" independent="" measurements="" performing="" when=""> L1 + K1A: normal output state</calculation>	
Switching functions for measurement mode	The measurement mode (diffuse reflective / specular reflective) can be switched between these two modes, in accordance with the sensor head selected, based on the measurement object.  Diffuse reflective mode: used when measuring a substance without a mirror surface or not transparent.  Specular reflective mode: used when measuring a substance with a mirror surface or is transparent.  When in specular reflective mode, the measurement object can be selected from the following options:  Standard: used when measuring the mirror surface of opaque substance such as metal, etc.  Front: used when measuring the surface of transparent substance such as glass, etc.  Rear: used when measuring the rear surface of transparent substance such as glass, etc.  The measurement center distance is shifted.  Thickness: used when measuring the thickness of transparent substance such as glass.  The refraction angle is compensated to 1.55. There is a limitation in measurable thickness. Thickness measurement guidelines for common glass sheets: General-purpose model – thicknesses 1.2 mm 0.047 in or more High precision model – thicknesses 0.5 mm 0.020 in or more  Thickness	
Low-pass filter function	For example, if the surface conditions of a metal object cause noise that interferes with accurate measurement, the use of the low-pass filter function will reduce the effects of noise and allow for the stable measurement of displacement. 9 independent cutoff frequencies can be selected, OFF or ranging from 10 to 2,000 Hz.	

## **Functions**

Function	Details		
High-pass filter function	If joints or grooves are being measured in the midst of great changes such as runout or inclination in an eccentric rotating object etc., this setting minimizes the effects of gradual changes and makes it possible to detect joints or grooves. 9 independent cutoff frequencies can be selected, OFF or ranging from 10 to 2,000 Hz.		
Switching function for average number of samples	If the measured values are subject to rapid fluctuation, then increasing the average number of samples will allow the unit to compensate for these fluctuations, enabling stable measurements to be obtained. The average number of samples can be selected from among 16 steps, ranging from OFF to 32,768 times.		
	The judgment output O1, O2 (NC) can be selected from the four types listed in the table below.    Copical output and judgment   Copical output and judg		
Judgment output selection function	O2 LOW Cose the lower limit value setting. The upper limit setting is ignored.  O1 LOW Cose the upper limit setting is ignored.  Select to distinguish between the upper limit and lower limit when the measurement value exceeds either limit.		
	O1 LOW or HIGH Cose   1   1   1		
	O1 LOGIC Cose Cose Cose Cose Cose Cose Cose Cos		
	* The output state is the state in which the terminal is open. (NC)		

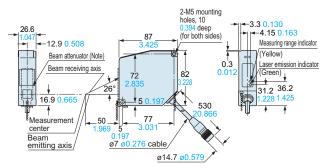
Function	Details
Hysteresis setting function	Optional hysteresis settings can be selected for both the upper and lower limits.
Analog output setting function	This function causes the output to correspond to the measurement value wanted at an analog output of +5 V (20 mA) and at -5 V (4 mA). It can be used for scaling of the analog output or for making the output greater or smaller, etc.  When this function is used, the analog output corresponding to measurement values ranging between, for example, 70 to 90 mm 2.756 to 3.543 in, can be assigned to outputs ranging from -5 V (for 70 mm 2.756 in) to +5 V (for 90 mm 3.543 in).
Analog output switching function during alarm	You can switch between the data having been output immediately before and a fixed value as an analog output issued when measurement is disabled (with an alarm output) due to an excessive or insufficient amount of light or deviation from the range. When the fixed value setting is selected, either the maximum value (voltage output: +10.9 V, current output: 29.5 mA) or minimum value (voltage output: -10.9 V, current output: 0 mA) of the analog output is issued during an alarm.
Input selection function	The timing signal at the input terminal functions as an input upon a short circuit by default setting. Use this function to activate the input upon an open circuit.
Calibration function	Measurement errors may occur due to the color, material or surface condition of the object being measured. These differences can be compensated for through calibration.  The calibration function allows the span and shift to be set for each sensor head. There are two ways to set these values. One is to conduct auto setting by moving a piece of the object past sensors and the other is to input previously measured values directly.
Display light received function	This function displays the peak level of light received at the measuring point.     The usage of this function when installing sensor heads allows the optimum marginal increment to be used as the level of light received for measurement.
Save function	This function saves all setting data except for the timing input state and display hold state.

## **HL-C108**□**-BK** Sensor head



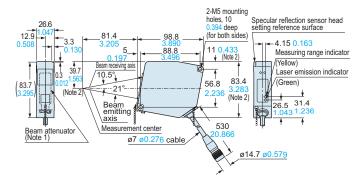
Note: There is not beam attenuator on IEC / JIS standards conforming type.

## HL-C105□-BK Sensor head



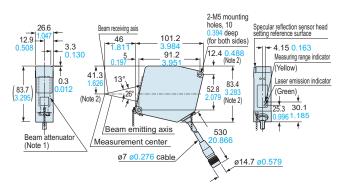
Note: There is not beam attenuator on IEC / JIS standards conforming type.

## HL-C108B HL-C108F



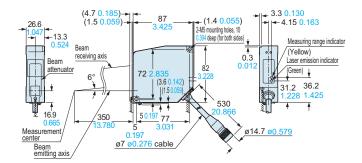
Notes: 1) There is not beam attenuator on IEC / JIS standards conforming type.
2) Figure shows standard installation level dimensions.

## HL-C105B HL-C105F Sensor head

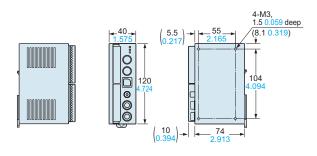


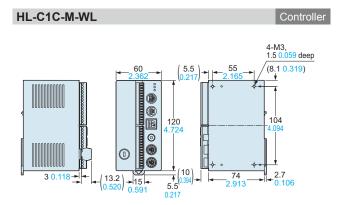
Notes: 1) There is not beam attenuator on IEC / JIS standards conforming type.
2) Figure shows standard installation level dimensions.

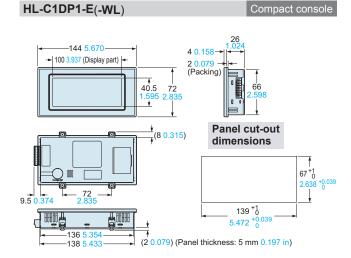
## HL-C135C-BK10 Sensor head

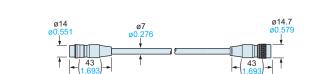


## HL-C1C-M Controller









## • Length L

HL-C1CCJ

Model No.	Length L (mm in)
HL-C1CCJ2	2,000 78.740
HL-C1CCJ5	5,000 196.850
HL-C1CCJ10	10,000 393.700
HL-C1CCJ20	20,000 787.400
HL-C1CCJ30	30,000 1181.100

All information is subject to change without prior notice.



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