

ROBO-8820VG2 Series

System Host Board

User's Manual

P/N: B8980950 Version 1.0

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How to Use This Manual

The manual describes how to configure your ROBO-8820VG2 series SHB to meet various operating requirements. It is divided into six chapters, with each chapter addressing a basic concept and operation of System Host Board (SHB).

Chapter 1: System Overview. Presents contents of package and a detailed overview of the product specifications and basic system architecture for this model of system host board.

Chapter 2: Hardware Configuration. Shows the definitions and locations of Jumpers and Connectors that you can easily configured for various system environment.

Chapter 3: System Installation. Describes how to properly mount the CPU, main memory and CompactFlash card to get a safe installation and provides a programming guide of Watch Dog Timer function.

Chapter 4: BIOS Setup Information. Specifies the meaning of each setup parameters. In addition, POST checkpoint list will give users some guidelines of trouble-shooting.

Chapter 5: Troubleshooting. Provides you a few useful tips to quickly startup the ROBO-8820VG2 operation. As basic hardware installation has been addressed in Chapter 3, this chapter will mainly focus on system integration matters, such as backplane setup, BIOS setting, and OS diagnostics.

Chapter 6: Appendix. Useful information is provided in this chapter. That includes mechanical drawing of ROBO-8820VG2 series with proprietary CPU cooler, memory address map and interrupt request lines (IRQs).

The content of this manual and EC declaration document is subject to change without prior notice. These changes will be incorporated in new editions of the document. **Portwell** may make supplement or change in the products described in this document at any time.

Updates to this manual, technical clarification, and answers to frequently asked questions will be shown on the following web site : <http://www.portwell.com.tw>

EC Declaration of Conformity (To Be Added)

For the following equipment:

Product Name:

Model Name:

Trade Name:

is herewith confirmed to comply with the requirements set out in the Council Directive on the Approximation of the Laws of the Member States relating to Electromagnetic Compatibility Directive (89/336/EEC). The equipment was evaluated and passed the test, the following standards were applied :

EMC :	EN 55022	(1994+A1;1995+A2;1997)
	EN 55024	(1998)
	EN 61000-3-2	(1995+A1;1998+A2;1998+A14)
	EN 61000-3-3	(1995)
	IEC 61000-4-2	(1995)
	IEC 61000-4-3	(1995)
	IEC 61000-4-4	(1995)
	IEC 61000-4-5	(1995)
	IEC-61000-4-6	(1996)
	IEC-61000-4-11	(1994)

The following manufacturer is responsible for this declaration :

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(Company Name)

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Taipei, R.O.C.
Place

Date

Legal Signature of
Authorized Person

Chapter 1

System Overview

1.1 Introduction

The ROBO-8820VG2 series based on Intel® E7501 chipset with 533 MHz system bus. The combination of dual Intel® Xeon™ processors optimized Intel® NetBurst™ micro-architecture and Hyper-Threading Technology creates a balanced platform with unparalleled price-performance, scalability and flexibility. Coupled with the dual port Intel® 82546EB Gigabit Controller, the board is a synergy of high computing and communication power to adapt to the diverse environment of medical/laboratory, industrial control and automation, instrumentation, data acquisition, transportation monitoring, COTS defense/aerospace and communication markets. ePCI-X (PICMG 1.2) is a new standard that is gaining traction in the embedded and communications market segments. The Intel® Xeon™ processor-based ePCI-X boards will provide high performance in very attractive form factors, allowing for implementation of communications, appliances and industrial control applications.

ROBO-8820VG2 utilizes dual channel DDR-266/200 memory to tremendously accelerate the speed of the data transaction, and it is capable of supporting up to 4 GB of registered DDR 266/200 ECC memory. Besides, the board also offers two independent PCI-X buses for further I/O expansion. The I/O bandwidth of PCI-X bus allows for delivering high volume of data traffic created by Gigabit Ethernet, SCSI, image processing and so on massive data flow applications. With dual independent bus design, it is flexible to accommodate legacy add-on cards with lower speed bus without sacrificing the performance of other high-speed add-on cards running in another bus.

A tailor-made thermal solution is provided to guarantee the highest reliability during peak workloads. In order to maximize the high-bandwidth I/O architecture of the Intel® E7501 chipset, up to another four additional full speed PCI-X buses are available through a specially designed interface.

Notice of ROBO-8820VG2 series:

ROBO-8820VG2 series are classified by dual Gigabit Ethernet port over copper or fiber connection and proprietary Hub Link 2.0 expansion connector. Following table helps you to identify the ROBO-8820VG2 series System Host Board.

Model Name	Copper GbE	Fiber GbE	Hub Link 2.0 Connector
ROBO-8820VG2	✓		
ROBO-8820VF2		✓	
ROBO-8820VG2H	✓		✓
ROBO-8820VF2H		✓	✓

1.2 Check List

The ROBO-8820VG2 series package should cover the following basic items -

- ✓ One ROBO-8820VG2 series system host board
- ✓ One proprietary CPU cooler
- ✓ Four screws with spring for 604-pin CPU and four for 603-pin CPU
- ✓ One dummy CPU pad for single 604-pin CPU and one for 603-pin single CPU
- ✓ Two AI block for regulator depends on 604-pin or 603-pin CPU was adopted
- ✓ One PA-I1KUC adapter board with bracket (For ROBO-8820VG2/VF2)
- ✓ One adapter cable for PA-I1KUC
- ✓ One IDE cable
- ✓ One FDC cable
- ✓ One Y-cable cable for PS/2 keyboard and mouse
- ✓ One Parallel & Serial port cables with bracket
- ✓ One Installation Resources CD-Title
- ✓ One booklet of ROBO-8820VG2 series manual

If any of these items is damaged or missing, please contact your vendor and keep all packing materials for future replacement and maintenance.

1.3 Product Specification

- **Main processor**
Single or dual Intel® 604-pin Xeon™ processor(s) at 533/400MHz front side (system) bus speed. (603-pin Xeon supported)
- **BIOS**
Phoenix (Award) system BIOS with 4Mb Flash ROM with easy upgrade function ACPI, DMI, Green function and Plug and Play Compatible
- **Main Memory**
Two DIMM sockets supporting up to 4GB of registered ECC DDR 266/200 SDRAM
Note:
Interleaved memory; requires memory modules to be installed in pairs. DDR 266 must be used with 533MHz FSB speed processors.
- **L2 Cache Memory**
512KB built-in Intel® Xeon™ Processor
- **Chipset**
Intel® E7501 MCH and ICH3-S chipset

- **Bus Interface**
 - Follow PICMG 1.2 Rev 1.0 standard (dual PCI-X buses)
 - Fully complies with PCI-X Addendum to the PCI Local Bus specification V1.0
 - PCI IDE Interface supporting two enhanced IDE ports up to four HDD devices with PIO mode 4 and Ultra DMA/33/66/100 mode transfer and Bus Master feature
- **Floppy Drive Interface**

Support one FDD port up to two floppy drives and 5-1/4"(360K, 1.2MB), 3-1/2" (720K, 1.2MB, 1.44MB, 2.88MB) diskette format and 3-mode FDD
- **Serial Ports**

Support two high-speed 16C550 compatible UARTs with 16-byte T/R FIFOs
- **Parallel Port**

Support one parallel port with SPP, EPP and ECP modes
- **USB Interface**

Support four USB (Universal Serial Bus) 1.1 ports for high-speed I/O peripheral devices
- **PS/2 Mouse and Keyboard Interface**

Supporting PS/2 mouse/keyboard connection through PA-I1KUC by Y-Cable separation
- **Auxiliary I/O Interfaces**

System reset switch, external speaker, Keyboard lock, Ethernet access LED and HDD active LED, etc.
- **Real Time Clock/Calendar (RTC)**

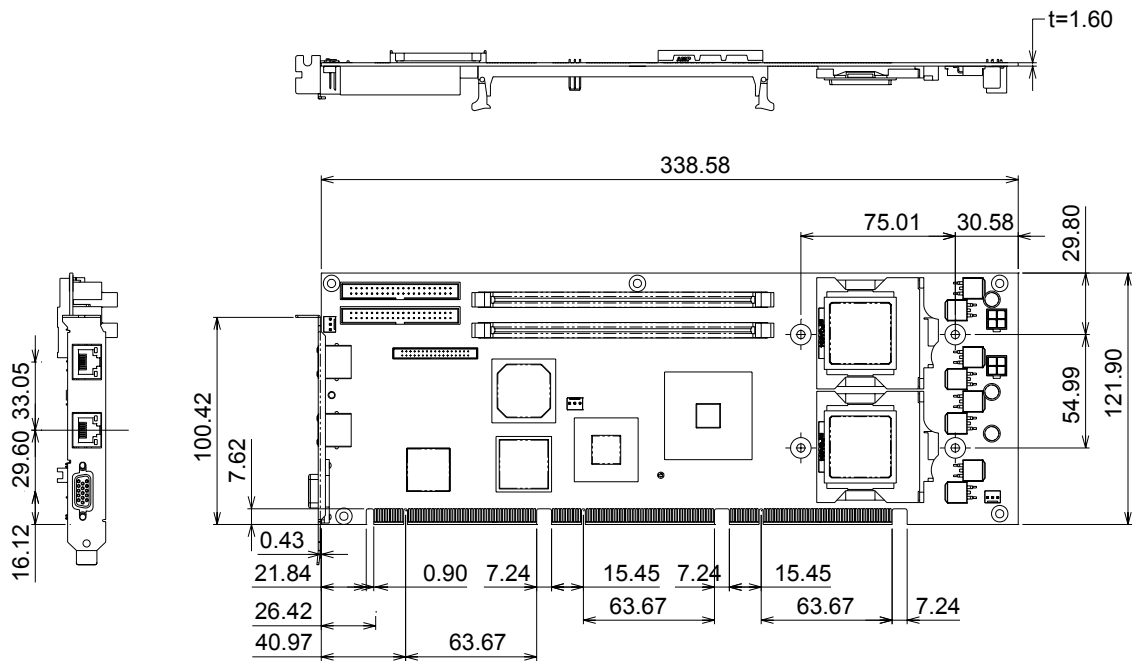
Support Y2K Real Time Clock/Calendar with battery backup for 7-year data retention
- **Watchdog Timer**
 - Support WDT function through software programming for enable/disable and interval setting
 - Generate system reset
- **CompactFlash Socket**
 - True IDE mode, compatibles with the ATA/ATAPI-4 specification
 - One Type II CF socket on secondary IDE channel for supporting up to 1GB memory
 - Bootable for no drives on primary channel
- **VGA Display**
 - ATI Rage XL graphic controller works in combination with a 8MB DDR-SDRAM.
 - Display resolution up to 1600 x 1200 @ 85Hz
- **On-board Gigabit Ethernet**

Intel® 82546EB PCI-X dual Gigabit Ethernet controller
- **Cooling Fan Power Connector**

Support three 3-pin connectors for CPU and System fans

- **System Monitoring Feature**
Monitor CPU temperature and major power sources, etc.
- **Bracket**
Support dual Ethernet port with 2 indicators (ROBO-8820VG2/VG2H), one and one CRT port
- **Outline Dimension (L x W):**
338.5mm (13.33") x 122mm (4.8")
- **CPU Cooler**
 - Dimension (L x W x H): 124 x 112 x 41 mm
 - Fan Speed: 1,000 rpm
 - Heat Sink Material: Copper
 - Rated Voltage: 12V DC
 - Thermal Resistance: 0.395
 - Weight: 970g
- **Power Requirements:**
 - +12V (CPU1) @ 3.7A
 - +12V (CPU2) @ 2.8A
 - +12V (System) @ 1.2A
 - +5V (System) @ 3.1A
 - +3.3V (System) @ 2.9A
- Test configuration:
 - CPU: Dual Intel® Xeon 2.0GHz/100MHz FSB/512KB L2 Cache
 - Memory: Dual DDR SDRAM 512MBx2
 - Primary Master IDE HDD: Seagate ST32042A (20GB)
 - OS: Windows Server 2000 with SP3
 - Test Programs: 3D Mark 2001 PRO and Burning Test V3.0
 - Connected Fans: Only CPU fan connected
 - Run Time: 10 minutes
- **Operating Temperature:**
-5°C ~ 50°C (23°F ~ 122°F)
- **Storage Temperature:**
-20°C ~ 80°C
- **Relative Humidity:**
0% ~ 95%, non-condensing

1.3.1 Mechanical Drawing



1.4 System Architecture

The architecture of ROBO-8820VG2 series includes Intel®'s memory controller hub E7510, I/O controller hub ICH3-S, Hub Link 2.0 to PCI/PCI-X bus bridge P64H2 and PCI-X interface dual Gigabit Ethernet controller 82546EB.

The E7501 chipset supports single or dual 533/400MHz Xeon™ processor, registered DDR 266/200 ECC SDRAM, ICH3-S supports PCI bus interface which was utilized to hook a ATI Rage XL graphic controller for the standard display requirement of server application, APM, ACPI compliant power management, USB port, SMBus communication, and Ultra DMA/33/66/100 IDE Master, bridge P64H2 providing two PCI-X buses of the system via golden finger of the SHB, 82546EB was on-board device attached to one of the PCI-X bus.

W83627HF (I/O Controller) is responsible for PS/2 Keyboard/Mouse, UARTs, FDC, Hardware Monitor, Parallel, Watch Dog Timer.

The propriety Hub Link 2.0 connector supports two additional P64H2 for additional four PCI/PCI-X buses for future extension.

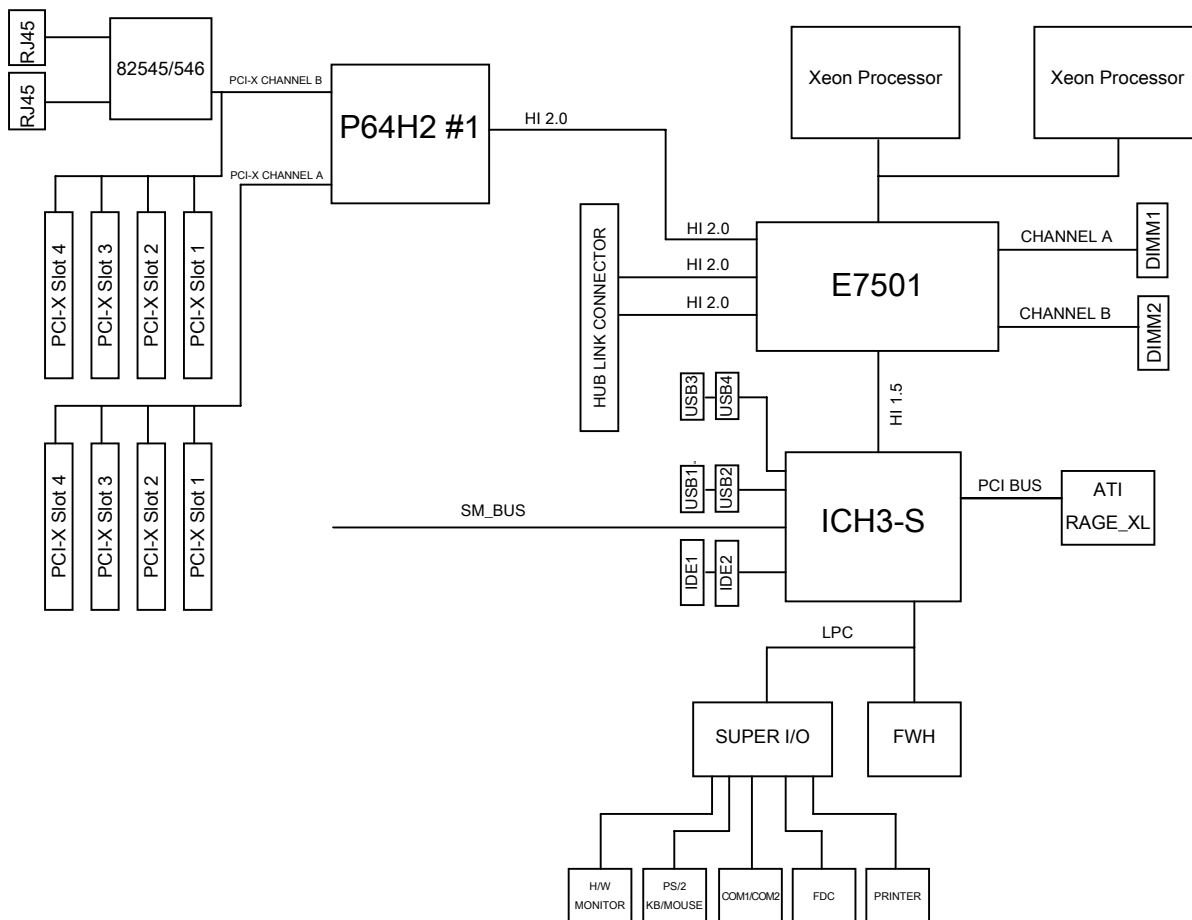


Figure 1-1 System Block Diagram of ROBO-8820VG2 series

Chapter 2

Hardware Configuration

This chapter indicates jumpers', headers' and connectors' locations. Users may find useful information related to hardware settings in this chapter. The default settings are indicated with a star sign (★).

2.1 Jumper Setting

For users to customize ROBO-8820VG2 series features. In the following sections, **Short** means covering a jumper cap over jumper pins; **Open** or **N/C** (Not Connected) means removing a jumper cap from jumper pins. Users can refer to Figure 2-1 for the Jumper locations.

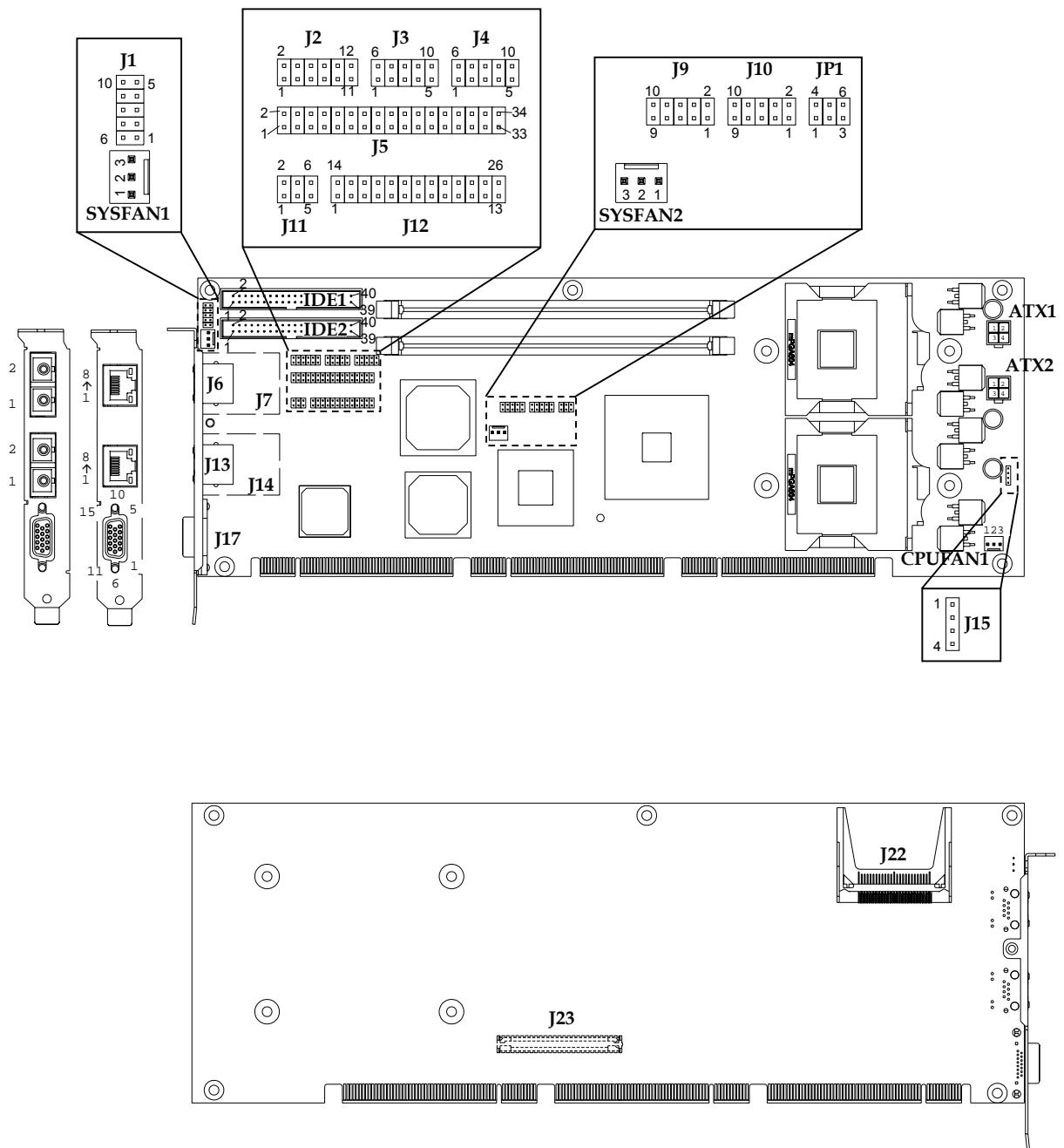


Figure 2-1 Jumper/Connector Location of ROBO-8820VG2 series

JP1: CMOS clear & AT Power Emulation

JP1	Function
1-2 short	ATX mode ★
2-3 short	AT Power Emulation
4-5 short	CMOS Normal ★
5-6 short	CMOS Clear

Note:

ROBO-8820VG2/VF2 only be evaluated in the environment with ATX power supply. "AT Power Emulation" means the ROBO-8820VG2/VF2 is able to be auto power up once power cord is plugged in ATX power supply. However, user need set BIOS setup menu "PWRON after PWR FAIL" to "ON" if you need auto power up function.

2.2 Connector Allocation

I/O peripheral devices and flash disk are connected to the interface connectors and DOC socket on this single board computer (Figure 2-1).

There is 26 pins 2mm cable included in the cable set, and the first RED LINE is the Pin 1 of the cable. This cable split to 3 cable groups. The first 10 pins cable group is for USB, the second 6 pins cable group is for PS2 KB/Mouse, and the third 10 pins cable group is for COM port.

Connector's Function List

Connector	Function	Remark
J1	Lan speed & Keylock	
J2	Misc	
J3	COM2 Serial Port	
J4	COM1 Serial Port	
J5	FDC	
J6/J13	Gigabit RJ45 Port B	ROBO-8820 VG2 only
J7/J14	Gigabit Fiber Port B	ROBO-8820 VF2 only
J8/J16	MCH Heat Sink Hooker	
J9	USB0, USB1 Connector	
J10	USB2, USB3 Connector	
J11	PS/2 keyboard/Mouse Connector	
J12	Print Port	
J13	Gigabit RJ45 Port A	ROBO-8820 VG2 only
J14	Gigabit Fiber Port A	ROBO-8820 VF2 only
J15	Speaker connector	
J17	VGA Port	
J21	Reserved for debugging	
J22	Compact Flash connector	
J23	Hyper Link Bus connector for additional PCI-X	Reserve for future use
IDE1	Primary IDE connector	
IDE2	Secondary IDE connector	

Pin Assignments of Connectors

J1: Lan speed & Keylock

PIN No.	Signal Description	PIN No.	Signal Description
1	VCC	6	LAN A ACT# (A+)
2	NC	7	LAN A LINK# (A-)
3	PWRLED	8	LAN B ACT# (B+)
4	KEYLOCK#	9	LAN B LINK# (B-)
5	GND	10	NC

Note:

Pin 1 ~ Pin5 is the connector for Keylock & Power LED function. Pin 6 ~ Pin10 is the connector for LAN LED function. LAN LED function is designed for LAN Link/Activity LED. Pin 6 is connected to LAN A LED anode, Pin 7 is connected to LAN A LED cathode. Pin 8 is connected to LAN B LED anode, Pin 9 is connected to LAN B LED cathode. Link/Activity LED will bright when link to a LAN port and twinkling while data transaction happening.

J2: Misc

PIN No.	Signal Description	PIN No.	Signal Description	Remark
1	HDD LED# (-)	2	VCC3 (+)	Pin 1 ~ 2 is for HDD LED
3	OVER Temp# (-)	4	VCC3 (+)	Pin 3 ~ 4 is for over temperature LED
5	RESET#	6	GND	Pin 5 ~ 6 is for reset button
7	GPIO32	8	3VSBY	Pin 7 ~ 8 is reserved
9	INTRUDER#	10	VCC_RTC	★ Pin9 ~ 10 is for Intruder detection, details see below.
11	AP Button	12	GND	See below

Note:

Pin 9 ~ 10 is Intruder detection button, default is short, it is used for chassis open detection. This button need to connect to chassis open detection mechanism if user need this function, and BIOS would show the warning message while booting if the chassis ever open. BIOS doesn't support this function yet, this function would be support in the near future.

Pin 11~ 12 is designed for those users who need "set to default" button. The methodology is that customer application can use this button to detect user press "set to default " then auto-configure the software environment to default setting or whatever you want. Please contact Portwell sales representative for application note if you need this function.

J3/J4: COM2/COM1 Serial Port 2/1 Connector

PIN No.	Signal Description
	RS-232
1	DCD (Data Carrier Detect)
2	RXD (Receive Data)
3	TXD (Transmit Data)
4	DTR (Data Terminal Ready)
5	GND (Ground)
6	DSR (Data Set Ready)
7	RTS (Request to Send)
8	CTS (Clear to Send)
9	RI (Ring Indicator)
10	N/C

Note:

The RED LINE of third cable group is connected to Pin 1 of the COM port connector.

J5: FDC Interface Connector

PIN No.	Signal Description	PIN No.	Signal Description
1	Ground	2	Density Select 0
3	Ground	4	N/C
5	Ground	6	Density Select 1
7	Ground	8	Index#
9	Ground	10	Motor ENA#
11	Ground	12	Drive Select B#
13	Ground	14	Drive Select A#
15	Ground	16	Motor ENB#
17	Ground	18	Direction#
19	Ground	20	Step#
21	Ground	22	Write Data#
23	Ground	24	Write Gate#
25	Ground	26	Track 0#
27	Ground	28	Write Protect#
29	N/C	30	Read Data#
31	Ground	32	Head Select#
33	N/C	34	Disk Change#

J6/J13: Gigabit RJ45 Port B

PIN No.	Signal Description
1	MD0 +
2	MD0 -
3	MD1 +
4	MD1 -
5	MD2 +
6	MD2 -
7	MD3 +
8	MD3 -

J7/J14: Gigabit Fiber Port B

PIN No.	Signal Description
1	RX
2	TX

J9/J10: USB Connector (USB0,USB1/USB2,USB3)

PIN No.	Signal Description	PIN No.	Signal Description
1	5V	2	Ground
3	USB0-/USB2-	4	Ground
5	USB0+/USB2+	6	USB1+/USB3+
7	Ground	8	USB1-/USB3-
9	Ground	10	5V

Note:

The RED LINE of first cable group is connected to Pin2 of USB port connector.

J11: PS/2 Keyboard/Mouse Connector

PIN No.	Signal Description
1	Mouse Data
2	Keyboard Data
3	Ground
4	5V
5	Mouse Clock
6	Keyboard Clock

Note:

The RED LINE of second cable group is connected to Pin 1 of PS/2 KB/Mouse connector

J12: Parallel Port Connector(Print Port)

PIN No.	Signal Description	PIN No.	Signal Description
1	Strobe#	14	Auto Form Feed#
2	Data 0	15	Error#
3	Data 1	16	Initialization#
4	Data 2	17	Printer Select IN#
5	Data 3	18	Ground
6	Data 4	19	Ground
7	Data 5	20	Ground
8	Data 6	21	Ground
9	Data 7	22	Ground
10	Acknowledge#	23	Ground
11	Busy	24	Ground
12	Paper Empty	25	Ground
13	Printer Select	26	N/C

J15: Speaker Connector

PIN No.	Signal Description
1	Speaker Signal Output
2	N/C
3	Ground
4	+5V

J17: VGA Port

PIN No.	Signal Description	PIN No.	Signal Description
1	R	9	VCC
2	G	10	GND
3	B	11	NC
4	NC	12	MONID 1
5	GND	13	HSYNC#
6	GND	14	VSYNC#
7	GND	15	MONID 2
8	GND		

IDE1/IDE2 : Primary/Secondary IDE Connector

PIN No.	Signal Description	PIN No.	Signal Description
1	RESET#	2	Ground
3	Data 7	4	Data 8
5	Data 6	6	Data 9
7	Data 5	8	Data 10
9	Data 4	10	Data 11
11	Data 3	12	Data 12
13	Data 2	14	Data 13
15	Data 1	16	Data 14
17	Data 0	18	Data 15
19	Ground	20	N/C
21	DMA REQ	22	Ground
23	IOW#	24	Ground
25	IOR#	26	Ground
27	IOCHRDY	28	Pull-down
29	DMA ACK#	30	Ground
31	INT REQ	32	N/C
33	DA1	34	CBLID#
35	DA0	36	DA2
37	HDC CS0#	38	HDC CS1#
39	HDD Active#	40	Ground

ATX1, ATX2

PIN No.	Signal Description
1	GND
2	GND
3	+12V
4	+12V

SYSFAN1, SYSFAN2, CPUFAN1

PIN No.	Signal Description
1	GND
2	+12V
3	Fan speed detection

Chapter 3

System Installation

This chapter provides instructions to set up your system. Additional information is enclosed to help you configuring CompactFlash card, and handle WDT operation in software programming.

Important Notice

In any case, user must take the end of CPU/CPU cooler to avoid the board damage as the result from the bend of the PCB.

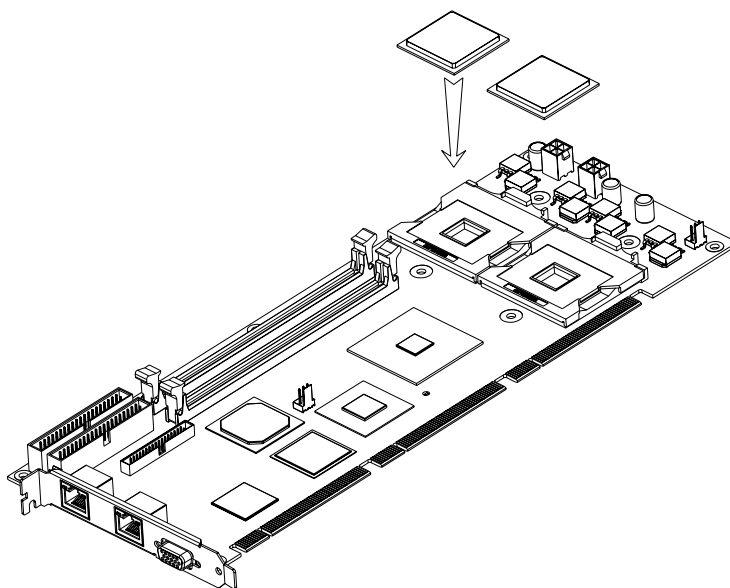
3.1 Xeon Processor

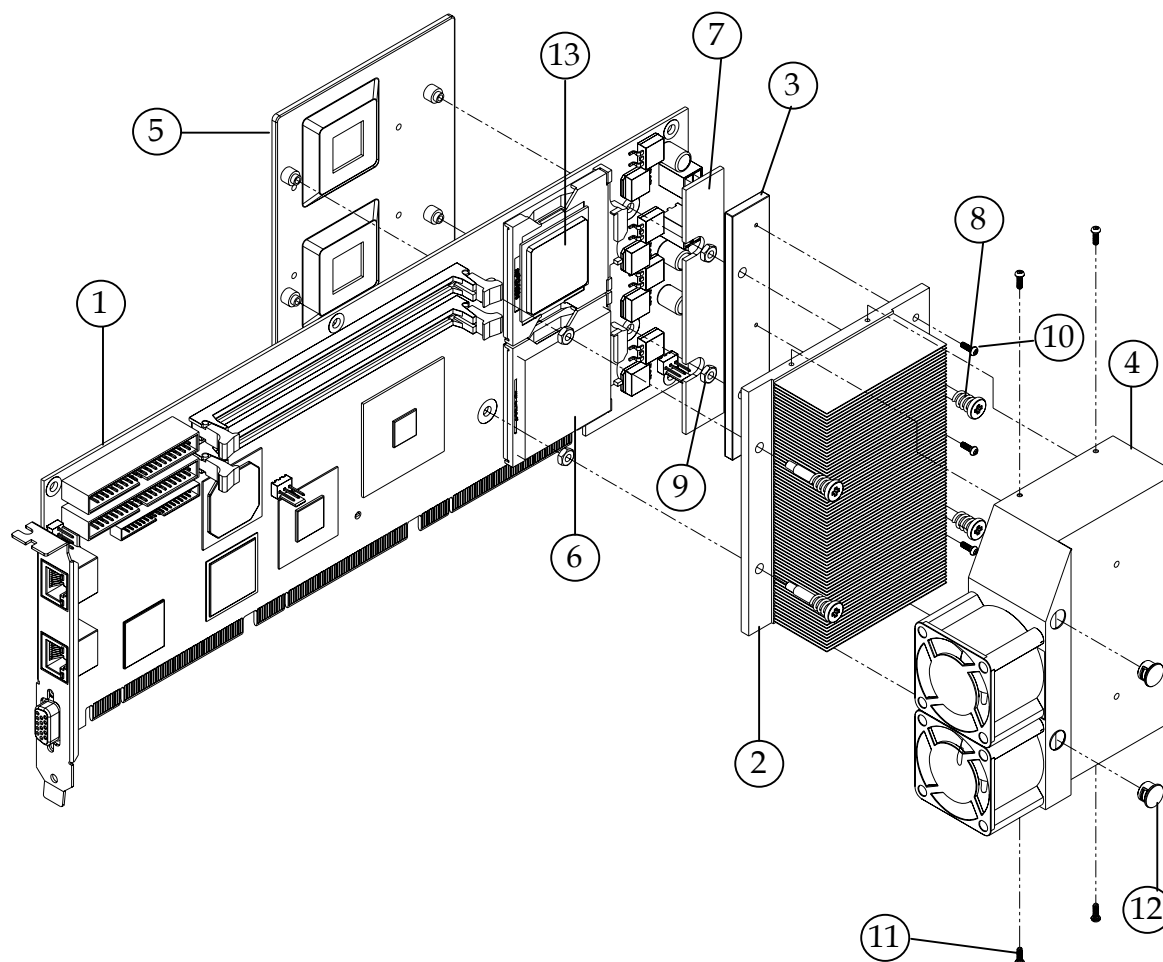
Installing Processor

- 1) Lift the handling lever of CPU socket outwards and upwards to the other end.
- 2) Align the processor pins with pinholes on the socket. Make sure that the notched corner or dot mark (pin 1) of the CPU corresponds to the socket's bevel end. Then press the CPU gently until it fits into place. If this operation is not easy or smooth, don't do it forcibly. You need to check and rebuild the CPU pin uniformly.
- 3) Push down the lever to lock processor chip into the socket once CPU fits.
- 4) Follow the installation guide of cooling fan or heat sink to mount it on CPU surface and lock it on the socket 478.

Note:

- 1) When dual CPU was applied, they must be the same core speed, bus speed and pin numbers.
- 2) When single CPU was applied, it must be installed in the socket near the DIMM.



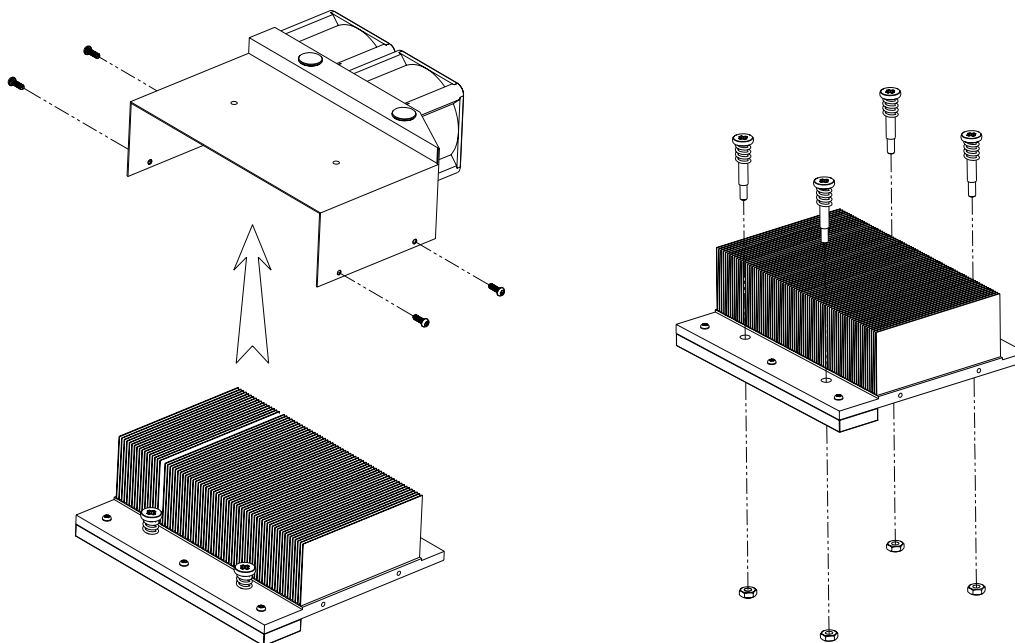
Identify CPU Cooler

Item	Description	Quantity
1	ROBO-8820VG2 Series SHB	1
2	Heat sink	1
3	Al block	2
4	Air duct	1
5	Cooler Backplate	1
6	Dummy CPU pad	2
7	Thermal pad	2
8	Cooler mounting screw and spring	8
9	Nut	4
10	Flat head M3 screw	3
11	Rounded head M2.5 screw	4
12	Cap for screw driver hole	2
13	Xeon processor	1 or 2

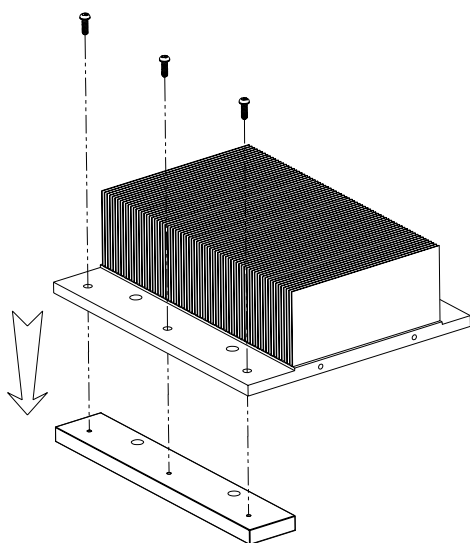
Install CPU Cooler

Case 1 : Single CPU

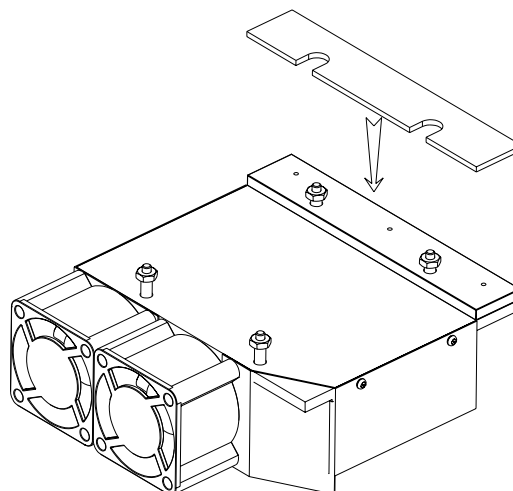
- 1) Adhere dummy pad on socket for no CPU in it
- 2) Change cooler mounting screws and spring if installation 603-pin Xeon by removing air duct and cooling fans (Longer cooler mounting screws are used for 603-pin Xeon processor)



- 3) Be sure to fix nuts tight on cooler mounting screws before install it on backplate
- 4) Change AI block on CPU cooler if installation 603-pin Xeon

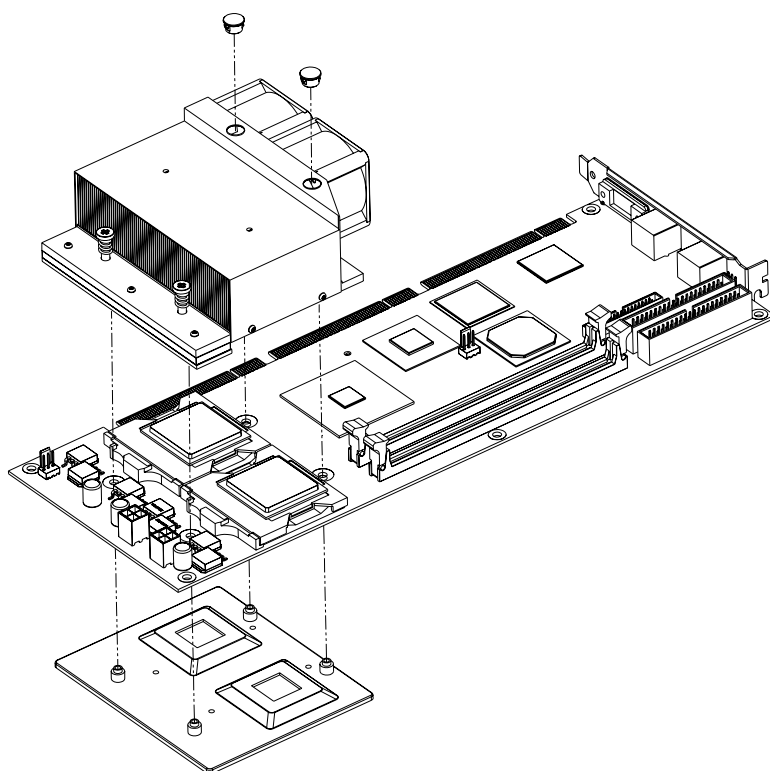


5) Adhere thermal pad on AI block according CPU type



6) Put cooler backplate at bottom of SHB

7) Tear off protection of thermal tape of thermal pad on AI block



8) Put CPU cooler on the SHB (Cooling fans near DIMM sockets)

9) Fixed screws of CPU cooler according 603-pin or 604-pin CPU

10) Cover the screw holes on air duct

Case 2 : Dual CPU

Same procedures as Case 1 except item 1

Removing CPU

- 1) Unlock the CPU cooler first
- 2) Lift the lever of CPU socket outwards and upwards to the other end
- 3) Carefully lifts up the existing CPU to remove it from the socket
- 4) Follow the steps of installing a CPU to change to another one or place handling bar to close the opened socket

3.2 Main Memory

ROBO-8820VG2 series provides two DDR-SDRAM DIMM slots to support 2.5V DDR-SDRAM as on-board main memory. The maximum memory size can be up to 4GB. Auto detecting memory clock according to BIOS CMOS settings.

For system compatibility and stability, please use branded memory modules. The memory scheme is interleaved therefore paired installation in required. If using 533MHz front side bus processor(s), DDR 266 SDRAM must be used. If using 400MHz front side bus processor(s), either DDR 266 or DDR 200 SDRAM is acceptable.

Please be aware of the contact and lock integrity of memory module with socket, it will subsequently impact on the system reliability. Follow normal procedures to install DRAM modules into memory socket. Before locking, make sure that all modules are fully inserted into the card slots.

Note:

To maintain system stability, don't change any of DRAM parameters in BIOS setup as system automatically selected optimal settings.

3.3 CompactFlash Card

ROBO-8820VG2 series reserves one Type II CompactFlash socket for installing CompactFlash card up to 1GB.

Installing CF

- 1) Carefully handle the card, always hold it by the edges. Holding the center of the card probably won't damage it, but holding the card by the edges provides an extra measure of protection.
- 2) Slide CompactFlash card into the socket.
- 3) If CompactFlash card doesn't slide into the socket easily, don't try to force it. It may be reversed. Turn it around and try inserting it again.

WARNING

- 1) Keep CompactFlash card away from direct sunlight, moisture, and magnetic fields.
- 2) The True IDE mode does not support hot insertion and removal because of the probable disruption of signals on the system bus.

3.4 Installing the System Host Board

To install your ROBO-8820VG2 series into standard chassis or proprietary environment, you need to perform the following:

Step 1: Check all jumpers setting on proper position

Step 2: Install and configure CPU, CPU cooler and memory module on right position

Step 3: Place ROBO-8820VG2 series into the dedicated position in your system

Step 4: Attach cables to existing peripheral devices and secure it

Step 5: Attach two 4-pin 12V power cables of ATX power supply to on board 12V CPU supplementary connectors (ATX1, ATX2)

WARNING

Please ensure that your SHB is properly inserted and fixed by mechanism. Otherwise, the system might be unstable or do not work due to bad contact of golden finger.

Note:

Please refer to section 3-4-1 to 3-4-3 to install INF/VGA/LAN drivers.

3.4.1 Driver Installation

The chipset on ROBO-8820VG2 series is a new chipset that a few old operating systems might not be able to recognize. To overcome this compatibility issue, for Windows Operating Systems such as Windows-95/98/98SE/2000, please install its INF before any of other Drivers are installed. Chipset device driver can be found in dirver disc. The driver disc has an Autorun program for easily installation drivers under Windows based OS. For other operating systems, please refer README file in the root directory to get driver directory information according to Intel E7501@ chipset and ROBO-8820VG2.

3.5 Clear CMOS Operation

The following table indicates how to enable/disable CMOS Clear Function hardware circuit by putting jumpers at proper position.

JP1	FUNCTION
4-5 Short	Normal Operation ★
5-6 Short	Clear CMOS Contents

To correctly operate CMOS Clear function, users must turn off the system, move JP1 jumper to short pin 5 and 6. To clear CMOS, please turn the power back on and turn it off again for AT system, or press the toggle switch a few times for ATX system. Move the JP1 back to 1-2 position (Normal Operation) and start the system. System will then produce a "CMOS Check Sum Error" message and hold up. Users may then follow the displayed message to load BIOS default setting.

3.6 Watch Dog Timer Function

The working algorithm of the WDT function can be simply described as a counting process. The Time-Out Interval can be set through software programming. The availability of the time-out interval settings by software or hardware varies from boards to boards.

The ROBO-8820VG2 series allows users control WDT through dynamic software programming. The WDT starts counting when it is activated. It sends out a signal to system reset, when time-out interval ends. To prevent the time-out interval from running out, a re-trigger signal will need to be sent before the counting reaches its end. This action will restart the counting process.

A well-written WDT program should keep the counting process running under normal condition. WDT should never generate a system reset or NMI signal unless the system runs into troubles.

The related Control Registers of WDT are all included in the following sample program that is written in C language. User can fill a non-zero value into the Time-out Value Register to enable/refresh WDT. System will be reset after the Time-out Value to be counted down to zero. Or user can directly fill a zero value into Time-out Value Register to disable WDT immediately.

To ensure a successful accessing to the content of desired Control Register, the sequence of following program codes should be step-by-step run again when each register is accessed.

Additionally, there are maximum 2 seconds of counting tolerance that should be considered into user' application program. For more information about WDT, please refer to Winbond W83627HF data sheet.

There are two PnP I/O port addresses that can be used to configure WDT,

- 1) 0x2E:EFIR (Extended Function Index Register, for identifying CR index number)
- 2) 0x2F:EFDR (Extended Function Data Register, for accessing desired CR)

Below are some example codes, which demonstrate the use of WDT.

```
// Enter Extended Function Mode
outp(0x002E, 0x87);
outp(0x002E, 0x87);
// Assign Pin 89 to be a WDIO
outp(0x002E, 0x2B);
outp(0x002F, inp(0x002F) & 0xEF);
// Select Logic Device 8
outp(0x002E, 0x07);
outp(0x002F, 0x08);
// Active Logic Device 8
outp(0x002E, 0x30);
outp(0x002F, 0x01);
// Select Count Mode
outp(0x002E, 0xF5);
outp(0x002F, (inp(0x002F) & 0xF7) | (Count-mode Register & 0x08));
// Specify Time-out Value
outp(0x002E, 0xF6);
outp(0x002F, (Time-out Value Register));
// Disable WDT reset by keyboard/mouse interrupts
outp(0x002E, 0xF7);
outp(0x002F, 0x00);
// Exit Extended Function Mode
outp(0x002E, 0xAA);
```

Definitions of Variables:

Value of **Count-mode Register**:

- 1) 0x00 -- Count down in seconds (Bit3=0)
- 2) 0x08 -- Count down in minutes (Bit3=1)

Value of **Time-out Value Register**:

- 1) 0x00 -- Time-out Disable
- 2) 0x01~0xFF -- Value for counting down

Chapter 4

BIOS Setup Information

ROBO-8820VG2 series is equipped with the Phoenix (AWARD) BIOS stored in Flash ROM. This BIOS has a built-in Setup program that allows users to modify the basic system configuration easily. This type of information is stored in CMOS RAM so that it is retained during power-off periods. When system is turned on, ROBO-8710VLA communicates with peripheral devices and check its hardware resources against the configuration information stored in the CMOS memory. If any error is detected, or the CMOS parameters need to be initially defined, the diagnostic program will prompt the user to enter the SETUP program. Some errors are significant enough to abort the start-up.

4.1 Entering Setup

Turn on or reboot the computer. When the message "Hit if you want to run SETUP" appears, press key immediately to enter BIOS setup program.

If the message disappears before you respond, but you still wish to enter Setup, please restart the system to try "COLD START" again by turning it OFF and then ON, or touch the "RESET" button. You may also restart from "WARM START" by pressing <Ctrl>, <Alt>, and <Delete> keys simultaneously. If you do not press the keys at the right time and the system will not boot, an error message will be displayed and you will again be asked to,

Press <F1> to Run SETUP or Resume

In HIFLEX BIOS setup, you can use the keyboard to choose among options or modify the system parameters to match the options with your system. The table below will show you all of keystroke functions in BIOS setup.

General Help	
↑ ↓ → ←	: Move
Enter	: Select
+ / - / PU / PD	: Value
ESC	: Exit
F1	: General Help
F2	: Item Help
F5	: Previous Values
F6	: Fail-Safe Defaults
F7	: Optimized Defaults
F9	: Menu in BIOS
F10	: Save

4.2 Main Menu

Once you enter ROBO-8820VG2 AWARD BIOS CMOS Setup Utility, you should start with the Main Menu. The Main Menu allows you to select from eleven setup functions and two exit choices. Use arrow keys to switch among items and press <Enter> key to accept or bring up the sub-menu.

Phoenix-Award Workstation BIOS CMOS Setup Utility

Standard CMOS Features Advanced BIOS Features Advanced Chipset Features Integrated Peripherals Power Management Setup PnP/PCI Configurations PC Health Status	Frequency/Voltage Control Load Fail-Safe Defaults Load Optimized Defaults Set Supervisor Password Set User Password Save & Exit Setup Exit Without Saving
Esc : Quit F10 : Save & Exit Setup	↑ ↓ ← → : Select Item
Time, Date, Hard Disk Type....	

Note:

It is strongly recommended to reload Optimized Setting if CMOS is lost or BIOS is updated.

4.3 Standard CMOS Features

This setup page includes all the items in a standard compatible BIOS. Use the arrow keys to highlight the item and then use the <PgUp>/<PgDn> or <+>/<-> keys to select the value or number you want in each item and press <Enter> key to certify it.

Follow command keys in CMOS Setup table to change **Date**, **Time**, **Drive type**, and **Boot Sector Virus Protection Status**.

■ **Screen shot**

Phoenix- Award Workstation BIOS CMOS Setup Utility
Standard CMOS Features

Date: (mm:dd:yy)	Mon, Jun 16 2003	Item Help
Time: (hh,mm,ss)	16:51:13	
▶ IDE PrimaryMaster	[ST320424A]	Menu Level ▶
▶ IDE Primary Slave	None	Change the day, month, year and century
▶ IDE Secondary Master	None	
▶ IDE Secondary Slave	None	
Drive A	1.44M, 3.5 in.	
Drive B	None	
Video	EGA/VGA	
Halt On	All, But Keyboard	
Based Memory	640K	
Extended Memory	260096K	
Total Memory	261120K	
↑↓→←: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults		

■ Menu selections

Item	Options	Description
Date	mm:dd:yy	Change the day, month, year and century
Time	hh:mm:ss	Change the internal clock
IDE Primary Master	Options are in its sub menu (described in 4.4 Table)	Press <Enter> to enter next page for detail hard drive settings
IDE Primary Slave	Options are in its sub menu (described in 4.4 Table)	Press <Enter> to enter next page for detail hard drive settings
IDE Secondary Master	Options are in its sub menu (described in 4.4 Table)	Press <Enter> to enter next page for detail hard drive settings
IDE Secondary Slave	Options are in its sub menu (described in 4.4 Table)	Press <Enter> to enter next page for detail hard drive settings
Drive A Drive B	None 360K, 5.25 in 1.2M, 5.25 in 720K, 3.5 in 1.44M, 3.5 in 2.88M, 3.5 in	Select the type of floppy disk drive installed in your system
Video	EGA/VGA CGA 40 CGA 80 MONO	Select the default video device
Halt On	All Errors No Errors All, but Keyboard All, but Diskette All, but Disk/Key	Select the situation in which you want the BIOS to stop the POST process and notify you
Base Memory	640K	Displays the amount of conventional memory detected during boot up
Extended Memory	N/A	Displays the amount of extended memory detected during boot up
Total Memory	N/A	Displays the total memory available in the system

4.4 IDE Adaptors Setup Menu

The IDE adaptors control the IDE devices, such as hard disk drive or cdrom drive. It uses a separate sub menu to configure each hard disk drive.

■ Screen shot

Phoenix- Award Workstation BIOS CMOS Setup Utility
IDE Primary Master

IDE HDD Auto-Detection	Press Enter	Item Help
IDE Primary Access Mode	Auto Auto	Menu Level ►
Capacity	20405MB	To auto-detect the HDD's size, head... on this channel
Cylinder	39535	
Head	16	
Precomp	0	
Landing Zone	39534	
Sector	63	
↑↓→←: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults		

Menu selections

Item	Options	Description
IDE HDD Auto-detection	Press Enter	To auto-detect the HDD's size, head ... on the channel
IDE Primary Master / Slave IDE Secondary Master / Slave	None Auto Manual	Selecting 'manual' lets you set the remaining fields on this screen. Selects the type of fixed disk. "User Type" will let you select the number of cylinders, heads, etc. Note: PRECOMP=65535 means NONE !
Access Mode	CHS LBA Large Auto	Choose the access mode for this hard disk
Capacity	Auto Display your disk drive size	Disk drive capacity (Approximated). Note that this size is usually slightly greater than the size of a formatted disk given by a disk checking program.
The following options are selectable only if the 'IDE Primary Master' item is set to 'Manual'		
Cylinder	Min = 0 Max = 65535	Set the number of cylinders for this hard disk.
Head	Min = 0 Max = 255	Set the number of read/write heads
Precomp	Min = 0 Max = 65535	**** Warning: Setting a value of 65535 means no hard disk
Landing zone	Min = 0 Max = 65535	****
Sector	Min = 0 Max = 255	Number of sectors per track

CPU L1 Cache/L2 Cache

These two categories speed up memory access. However, it depends on CPU/chipset design.

Enabled	Enable cache
Disabled	Disable cache

Hyper-Threading Technology

“Enabled” for Windows XP and Linux 2.4X (OS optimized for Hyper-Threading Technology) and “Disabled” for OS not optimized for Hyper-Threading Technology.

The choice: Enabled, Disabled.

Quick Power On Self Test

Allows the system to skip certain tests while booting. This will decrease the time needed to boot the system.

Enabled	Enable quick POST
Disabled	Normal POST

First/Second/Third/Other Boot Device

The BIOS attempts to load the operating system from the devices in the sequence selected in these items.

The choice: Floppy, LS120, HDD-0, SCSI, CDROM, HDD-1, HDD-2 HDD-3, ZIP100, USB-FDD, USB-ZIP, USB-CDROM, USB-HDD, LAN and Disabled.

Other Boot Device

The choice: Enabled, Disabled.

Swap Floppy Drive

If the system has two floppy drives, choose enable to assign physical driver B to logical drive A and Vice-Versa.

The choice: Enabled, Disabled.

Boot Up Floppy Seek

Enabled tests floppy drives to determine whether they have 40 or 80 tracks

The choice: Enabled, Disabled.

Boot Up NumLock Status

Select power on state for NumLock.

The choice: Off, On.

Get A20 Option

Fast-lets chipsets control Gate A20 and normal - a pin in the keyboard controller controls Gate A20. Default is Fast.

The choice: Normal, Fast.

Typematic Rate Setting

Keystrokes repeat at a rate determined by the keyboard controller - When enabled, the typematic rate and typematic delay can be select.

The choice: Enabled, Disabled.

Typematic Rate (Chars/sec)

The rate at which character repeats when you hold down a key.

The choice: 6, 8, 10, 12, 15, 20, 24, 30.

Typematic delay (Msec)

The delay before key strokes begin to repeat.

The choice: 250, 500, 750, 1000.

Security Option

Select whether the password is required every time the system boots or only when you enter setup.

System	The system will not boot and access to Setup will be denied if the correct password is not entered at the prompt.
Setup	The system will boot, but access to Setup will be denied if the correct password is not entered at the prompt.

Note:

To disable security, select PASSWORD SETTING at Main Menu and then you will be asked to enter password. Do not type anything and just press <Enter>, it will disable security. Once the security is disabled, the system will boot and you can enter Setup freely.

Console Redirection

Enable - Attempt to redirect console via COM port.

Disable - Attempt to redirect console when keyboard absent.

Baud Rate

Specify Baud Rate of console redirection.

The choice: 9600, 19200, 38400, 57600, 115200.

Agent Connect via

Connection modes: NULL - Direct connection Agent wait time (min).

Agent wait time (min)

Timeout for connection.

The choice: 1, 2, 4, 8.

Agent after boot

Keep Agent running after OS boot.

The choice: Enabled, Disabled.

4.6 Advanced Chipset Features

This section allows you to configure the system based on the specific features of the Intel 82845E chipset. This chipset manages bus speeds and access to system memory resources, such as DRAM (SDRAM) and the external cache. It also coordinates communications between the conventional ISA bus and the PCI bus. It must be stated that these items should never need to be altered. The default settings have been chosen because they provide the best operating conditions for your system. The only time you might consider making any changes would be if you discovered that data was being lost while using your system.

■ **Screen shot**

Phoenix - Award Workstation BIOS CMOS Setup Utility
Advanced Chipset Features

DRAM Timing Control	Press Enter	Item Help
DRAM Data Integrity Mode	ECC	
System BIOS Cacheable	Enabled	Menu Level ▶
Video BIOS Cacheable	Disabled	
Memory Hole AT 15-16M	Disabled	
↑↓←→: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults		

This chipset settings deal with CPU access to dynamic random access memory (DRAM). The default timings have been carefully chosen and should only be altered if data is being lost. Such a scenario might well occur if your system had mixed speed DRAM chips installed so that greater delays may be required to preserve the integrity of the data held in the slower memory chips.

DRAM Timing Control

Press Enter for DRAM Timing Control Setup.

DRAM Data Integrity Mode

There are two options available. The DRAM integrity mode will be implemented by the parity algorithm when this option is set to “Non-ECC”.

The choice: Non ECC, ECC.

System BIOS Cacheable

Selecting Enabled allows caching of the system BIOS ROM at F0000h-FFFFFh, resulting in better system performance. However, if any program writes to this memory area, a system error may result.

The choice: Enabled, Disabled.

Video BIOS Cacheable

Select “Enabled” to enable caching VGA BIOS into L2 cache to get higher display performance. “Disabled” to ignore this BIOS caching function.

The choice: Enabled, Disabled.

Memory Hole At 15-16M

In order to improve performance, certain space in memory is reserved for ISA cards. This memory must be mapped into the memory space below 16MB.

The choice: Enabled, Disabled.

■ **Screen shot**

Phoenix – Award Workstation BIOS CMOS Setup Utility
DRAM Timing Control

DRAM Timing Configure	By SPD	Item Help
X - CAS Latency Time	2	Menu Level ▶
X - Active to Precharge Delay	5	
X - DRAM RAS# to CAS# Delay	2	
X - DRAM RAS# Precharge	2	
↑↓←→: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults		

DRAM Timing Configure

This option provides DIMM plug-and-play support by serial presence detect (SPD) mechanism via the system management bus (SMBUS) interface.

The choice: Manual, By SPD.

CAS Latency Time

This option controls the number of SCLKs between the time a read command is sampled by the SDRAMs and the time the GMCH samples correspondent data from the SDRAMs.

The choice: 1.5, 2, 2.5 SCLKs.

Active to Precharge Delay

This is to DDR standard accordingly.

The choice: 7, 6, 5.

DRAM RAS# to CAS# Delay

This option controls the number of SCLKs (SDRAM Clock) from a row activate command to a read or write command. If your system installs good quality of SDRAM, you can set this option to "3 SCLKs" to obtain better memory performance. Normally, the option will be set to Auto.

The choice: 2 or 3.

DRAM RAS# Precharge

This option controls the number of SCLKs for RAS# precharge. If you system installs good quality of SDRAM, you can set this option to "3 SCLKs" to obtain better memory performance. It is set to auto normally.

4.7 Integrated Peripherals

■ Screen shot

Phoenix - Award Workstation BIOS CMOS Setup Utility
Integrated Peripherals

<ul style="list-style-type: none"> ▶ OnChip IDE Device [Press Enter] ▶ Onboard Device [Press Enter] ▶ Supper IO Device [Press Enter] 	Item Help
	Menu Level ▶
↑↓←→: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults	

OnChip IDE Device

Press Enter for OnChip IDE Device Setup.

■ **Screen shot**

Phoenix - Award Workstation BIOS CMOS Setup Utility
OnChip IDE Device

IDE HDD Block Mode [Enabled] On-Chip Primary PCI IDE [Enabled] IDE Primary Master PIO [Auto] IDE Primary Slave PIO [Auto] IDE Primary Master UDMA [Auto] IDE Primary Slave UDMA [Auto] On-Chip Secondary PCI IDE [Enabled] IDE Secondary Master PIO [Auto] IDE Secondary Slave PIO [Auto] IDE Secondary Master UDMA [Auto] IDE Secondary Slave UDMA [Auto]	Item Help <hr/> Menu Level ▶
↑↓←→: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults	

OnChip Primary/Secondary PCI IDE

The chipset contains a PCI IDE interface with support for two IDE channels. Select Enabled to activate the primary IDE interface. Select Disabled to deactivate this interface.

The choice: Enabled, Disabled.

IDE Primary/Secondary Master/Slave PIO

The four IDE PIO (Programmed Input/Output) fields let you set a PIO mode (0-4) for each of the four IDE devices that the onboard IDE interface supports. Modes 0 through 4 provide successively increased performance. In Auto mode, the system automatically determines the best mode for each device.

The choice: Auto, Mode 0, Mode 1, Mode 2, Mode 3, Mode 4.

IDE Primary/Secondary Master/Slave UDMA

Ultra DMA/33/66/100 implementation is possible only if your IDE hard drive supports it and the operating environment includes a DMA driver (Windows 95 OSR2 or a third-party IDE bus master driver). If your hard drive and your system software both support Ultra DMA/33/66/100, select Auto to enable BIOS support.

The choice: Auto, Disabled.

Onboard Device

Press Enter for Onboard Device Setup.

■ **Screen shot**

Phoenix - Award Workstation BIOS CMOS Setup Utility
Onboard Device

USB Controller	[Enabled]	Item Help
USB Keyboard Support	[Enabled]	
		Menu Level ▶
↑↓←→: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults		

USB Controller

This item allows you to enable/disable USB (Universal Serial Bus) function.

The choice: Enabled, Disabled.

USB Keyboard Support

This item allows you to enable USB keyboard function under POST, BIOS setup menu, DOS, or Windows-NT with no USB driver loaded.

The choice: Enabled, Disabled.

Super IO Device

Press Enter for Super IO Device Setup.

■ **Screen shot**

Phoenix - Award Workstation BIOS CMOS Setup Utility
Super IO Device

Onboard FDC Controller	[Enabled]	Item Help
Onboard Serial Port 1	[3F8/IRQ4]	
Onboard Serial Port 2	[2F8/IRQ3]	Menu Level ▶
Onboard Parallel Port	[378/IRQ7]	
Parallel Port Mode	[ECP]	
X EPP Mode Select	EPP1.9	
ECP Mode Use DMA	[3]	
PWRON After PWR-Fail	[off]	
↑↓←→: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults		

Onboard Serial Port1/Port2

Select an address and corresponding interrupt for the first and second serial ports.

The choice: 3F8/IRQ4, 2E8/IRQ3, 3E8/IRQ4, 2F8/IRQ3, Disabled, Auto.

Onboard Parallel Port

This item allows you to configure I/O address of the onboard parallel port.

The choice: Disabled, 378/IRQ7, 278/IRQ5, 3BC/IRQ7.

Parallel Port Mode

There are four different modes for the onboard parallel port:

SPP	Switch to SPP mode
EPP	Switch to EPP mode
ECP	Switch to ECP mode
ECP+EPP	Switch to ECP + EPP mode
Normal	Switch to Normal mode

EPP Mode Select

Select different version of EPP mode.

The choice: EPP1.7, EPP1.9.

ECP Mode Use DMA

Select a proper DMA channel for ECP mode.

The choice: 3, 1.

PWRON After PWR-Fail

This item allows user to configure the power status of using ATX power supply after a serious power loss occurs.

On	System automatically restores power back
Off	System stays at power-off

Power Management

This category allows you to select the type (or degree) of power saving and is directly related to "HDD Power Down", "Suspend Mode".

There are three selections for Power Management, three of which have fixed mode settings.

Min. Power Saving	Minimum power management. Suspend Mode = 1 Hour, and HDD Power Down = 15 Min.
Max. Power Saving	Maximum power management. Suspend Mode = 1 Min., and HDD Power Down = 1 Min.
User Defined	Allows you to set each mode individually. When not disabled, Suspend Mode ranges from 1 min. to 1 Hour and HDD Power Down ranges from 1 Min. to 15 Min.

Video Off Method

This determines the manner in which the monitor is blanked.

V/H SYNC+Blank	This selection will cause the system to turn off the vertical and horizontal synchronization ports and write blanks to the video buffer.
Blank Screen	This option only writes blanks to the video buffer.
DPMS	Initial display power management signaling.

Video Off In Suspend

This allows user to enable/disable video off in Suspend Mode.

The choice: Yes, No.

Suspend Type

Two options are available : Stop Grant and PwrOn Suspend.

The choice: Stop Grant, PwrOn Suspend.

Suspend Mode

When enabled and after the set time of system inactivity, all devices except the CPU will be shut off.

The choice: Disabled, 1 Min, 2 Min, 4 Min, 8 Min, 12 Min, 20 Min, 30 Min, 40 Min, 1 Hour.

HDD Power Down

When enabled and after the set time of system inactivity, the hard disk drive will be powered down while all other devices remain active.

The choice: Disabled, 1 Min, 2 Min, 3 Min, 4 Min, 5 Min, 6 Min, 7 Min, 8 Min, 9 Min, 10 Min, 11 Min, 12 Min, 13 Min, 14 Min, 15 Min.

Soft-Off by PWR-BTTN

This item allows users to set the time to remove the power after the power button is pressed.

The choice: Instant-Off, Delay 4 Sec.

Intruder# Detection

The choice: Enabled, Disabled.

Wake-Up by LAN Device

This option can be enabled to support Wake Up by LAN device.

The choice: Disabled, Enabled.

Power On by Ring

When select "Enabled", a system that is at soft-off mode will be alert to Wake-On-Modem signal.

The choice: Enabled, Disabled.

Resume by Alarm

This item allows users to enable/disable the resume by alarm function. When "Enabled" is selected, system using ATX power supply could be powered on if a customized time and day is approached.

The choice: Enabled, Disabled.

Date(of Month) Alarm

When "Resume by Alarm" is enabled, this item could allow users to configure the date parameter of the timing dateline on which to power on the system.

The choices: 0 ~ 31.

Time(hh:mm:ss) Alarm

When "Resume by Alarm" is enabled, this item could allow users to configure the time parameter of the timing dateline on which to power on the system.

The choice: hh (0~23), mm (0~59), ss (0 ~59).

Primary/Secondary IDE 0/1

This item is to configure IDE devices being monitored by system so as to keep system out of suspend mode if the associated device is busy.

The choice: Enabled, Disabled.

FDD, COM, LPT Port

This item is to configure floppy device, COM ports, and parallel port being monitored by system so as to keep system out of suspend mode if the associated device is busy.

The choice: Enabled, Disabled.

PCI PIQ[A-D]#

This option can be used to detect PCI device activities. If they are activities, the system will go into sleep mode.

The choice: Enabled, Disabled.

4.9 PnP/PCI Configurations

This section describes configuring the PCI bus system. PCI, or Personal Computer Interconnect, is a system which allows I/O devices to operate at speeds nearing the speed the CPU itself uses when communicating with its own special components.

This section covers some very technical items and it is strongly recommended that only experienced users should make any changes to the default settings.

■ **Screen shot**

Phoenix - Award Workstation BIOS CMOS Setup Utility
PnP/PCI Configurations

PnP OS Installed	[Yes]	Item Help Menu Level ▶ BIOS can automatically configure all the boot and Plug and Play compatible devices. If you choose Auto, you cannot select IRQ DMA and memory base address fields, since BIOS automatically assigns them
Reset Configuration Data	Disabled	
Resources Controlled By	Auto(ESCD)	
X IRQ Resources	Press Enter	
PCI/VGA Palette Snoop	Disabled	
↑↓→←: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults		

PNP OS Installed

Select Yes if you are using a Plug and Play capable operating system. Select No if you need the BIOS to configure non-boot devices.

The choice: Yes, No.

Reset Configuration Data

Default is Disabled. Select Enabled to reset Extended System Configuration Data (ESCD) when you have installed a new add-on and the system reconfiguration has caused such a serious conflict that the OS cannot boot.

The choice: Enabled, Disabled.

Resource Controlled By

BIOS can automatically configure all the boot and plug and play compatible devices. If you choose Auto, you cannot select IRQ DMA and memory base address fields, since BIOS automatically assigns them.

The choice: Auto (ESCD), Manual.

IRQ Resources

When resources are controlled manually, assign each system interrupt a type, depending on the type of device using the interrupt.

The choice: Press Enter.

IRQ-3/IRQ-4/IRQ-5/IRQ-7/IRQ-9/IRQ-10/IRQ-11/IRQ-12/IRQ-14/IRQ-15 assigned, PCI PnP for devices compliant with the plug and play standard whether designed for PCI bus architecture.

The choice: PCI Device, Reserved.

PCI/VGA Palette Snoop

Leave this field at Disabled.

The choice: Enabled, Disabled.

4.10 PC Health Status

■ Screen shot

Phoenix - Award Workstation BIOS CMOS Setup Utility
PC Health Status

CPU 1 TEMP	37°C/98°F	Item Help	
CPU 2 TEMP	35°C/95°F	Menu Level ►	
Current CPU FAN1 Speed	10546RPM		
Current SYS FAN1 Speed	7670RPM		
Current SYS FAN2 Speed	12053RPM		
CPU	1.45V		
+2.5V	2.48V		
+3.3V	3.36V		
+5V	5.10V		
+12V	12.03V		
-12V	-12.03V		
5VSB(V)	4.96V		
↑↓→←: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults			

4.11 Frequency/Voltage Control

■ Screen shot

Phoenix - Award Workstation BIOS CMOS Setup Utility
Frequency/Voltage Control

CPU Clock Ratio	[16X]	Item Help
		Menu Level ►
↑↓→←: Move Enter: Select +/-/PU/PD: Value F10: Save ESC: Exit F1: General Help F5: Previous Values F6: Fail-Safe Defaults F7: Optimized Defaults		

4.12 Default Menu

Selecting “Defaults” from the main menu shows you two options which are described below

Load Fail-Safe Defaults

When you press <Enter> on this item you get a confirmation dialog box with a message similar to:

Load Fail-Safe Defaults (Y/N) ? **N**

Pressing ‘Y’ loads the BIOS default values for the most stable, minimal-performance system operations.

Load Optimized Defaults

When you press <Enter> on this item you get a confirmation dialog box with a message similar to:

Load Optimized Defaults (Y/N) ? **N**

Pressing ‘Y’ loads the default values that are factory settings for optimal performance system operations.

4.13 Supervisor/User Password Setting

You can set either supervisor or user password, or both of them. The differences between are:

Set supervisor password : can enter and change the options of the setup menus.

Set user password : just can only enter but do not have the right to change the options of the setup menus. When you select this function, the following message will appear at the center of the screen to assist you in creating a password.

ENTER PASSWORD

Type the password, up to eight characters in length, and press <Enter>. The password typed now will clear any previously entered password from CMOS memory. You will be asked to confirm the password. Type the password again and press <Enter>. You may also press <Esc> to abort the selection and not enter a password.

To disable a password, just press <Enter> when you are prompted to enter the password. A message will confirm the password will be disabled. Once the password is disabled, the system will boot and you can enter Setup freely.

PASSWORD DISABLED

When a password has been enabled, you will be prompted to enter it every time you try to enter Setup. This prevents an unauthorized person from changing any part of your system configuration.

Additionally, when a password is enabled, you can also require the BIOS to request a password every time your system is rebooted. This would prevent unauthorized use of your computer.

You determine when the password is required within the BIOS Features Setup Menu and its Security option (see Section 3). If the Security option is set to "System", the password will be required both at boot and at entry to Setup. If set to "Setup", prompting only occurs when trying to enter Setup.

4.14 Exiting Selection

Save & Exit Setup

Pressing <Enter> on this item asks for confirmation:

Save to CMOS and EXIT (Y/N)? **Y**

Pressing "Y" stores the selections made in the menus in CMOS – a special section of memory that stays on after you turn your system off. The next time you boot your computer, the BIOS configures your system according to the Setup selections stored in CMOS. After saving the values the system is restarted again.

Exit Without Saving

Pressing <Enter> on this item asks for confirmation:

Quit without saving (Y/N)? **N**

This allows you to exit Setup without storing in CMOS any change. The previous selections remain in effect. This exits the Setup utility and restarts your computer.

4.15 POST Messages

During the Power On Self-Test (POST), if the BIOS detects an error requiring you to do something to fix, it will either sound a beep code or display a message. If a message is displayed, it will be accompanied by:

PRESS F1 TO CONTINUE, CTRL-ALT-ESC OR DEL TO ENTER SETUP

POST Beep

Currently there are two kinds of beep codes in BIOS. This code indicates that a video error has occurred and the BIOS cannot initialize the video screen to display any additional information. This beep code consists of a single long beep followed by two short beeps. The other code indicates that your DRAM error has occurred. This beep code consists of a single long beep repeatedly.

Error Messages

One or more of the following messages may be displayed if the BIOS detects an error during the POST. This list includes messages for both the ISA and the EISA BIOS.

CMOS BATTERY HAS FAILED

CMOS battery is no longer functional. It should be replaced.

CMOS CHECKSUM ERROR

Checksum of CMOS is incorrect. This can indicate that CMOS has become corrupt. This error may have been caused by a weak battery. Check the battery and replace if necessary.

DISK BOOT FAILURE, INSERT SYSTEM DISK AND PRESS ENTER

No boot device was found. This could mean that either a boot drive was not detected or the drive does not contain proper system boot files. Insert a system disk into Drive A: and press <Enter>. If you assumed the system would boot from the hard drive, make sure the controller is inserted correctly and all cables are properly attached. Also be sure the disk is formatted as a boot device. Then reboot the system.

DISKETTE DRIVES OR TYPES MISMATCH ERROR - RUN SETUP

Type of diskette drive installed in the system is different from the CMOS definition. Run Setup to reconfigure the drive type correctly.

DISPLAY SWITCH IS SET INCORRECTLY

Display switch on the motherboard can be set to either monochrome or color. This indicates the switch is set to a different setting than indicated in Setup. Determine which setting is correct, and then either turn off the system and change the jumper, or enter Setup and change the VIDEO selection.

DISPLAY TYPE HAS CHANGED SINCE LAST BOOT

Since last powering off the system, the display adapter has been changed. You must configure the system for the new display type.

EISA Configuration Checksum Error PLEASE RUN EISA CONFIGURATION UTILITY

The EISA non-volatile RAM checksum is incorrect or cannot correctly read the EISA slot. This can indicate either the EISA non-volatile memory has become corrupt or the slot has been configured incorrectly. Also be sure the card is installed firmly in the slot.

EISA Configuration Is Not Complete PLEASE RUN EISA CONFIGURATION UTILITY

The slot configuration information stored in the EISA non-volatile memory is incomplete.

Note:

When either of these errors appear, the system will boot in ISA mode, which allows you to run the EISA Configuration Utility.

ERROR ENCOUNTERED INITIALIZING HARD DRIVE

Hard drive cannot be initialized. Be sure the adapter is installed correctly and all cables are correctly and firmly attached. Also be sure the correct hard drive type is selected in Setup.

ERROR INITIALIZING HARD DISK CONTROLLER

Cannot initialize controller. Make sure the cord is correctly and firmly installed in the bus. Be sure the correct hard drive type is selected in Setup. Also check to see if any jumper needs to be set correctly on the hard drive.

FLOPPY DISK CNTRLR ERROR OR NO CNTRLR PRESENT

Cannot find or initialize the floppy drive controller. Make sure the controller is installed correctly and firmly. If there are no floppy drives installed, be sure the Diskette Drive selection in Setup is set to NONE.

Invalid EISA Configuration PLEASE RUN EISA CONFIGURATION UTILITY

The non-volatile memory containing EISA configuration information was programmed incorrectly or has become corrupt. Re-run EISA configuration utility to correctly program the memory.

Note:

When this error appears, the system will boot in ISA mode, which allows you to run the EISA Configuration Utility.

KEYBOARD ERROR OR NO KEYBOARD PRESENT

Cannot initialize the keyboard. Make sure the keyboard is attached correctly and no keys are being pressed during the boot.

If you are purposely configuring the system without a keyboard, set the error halt condition in Setup to HALT ON ALL, BUT KEYBOARD. This will cause the BIOS to ignore the missing keyboard and continue the boot.

Memory Address Error at ...

Indicates a memory address error at a specific location. You can use this location along with the memory map for your system to find and replace the bad memory chips.

Memory parity Error at ...

Indicates a memory parity error at a specific location. You can use this location along with the memory map for your system to find and replace the bad memory chips.

MEMORY SIZE HAS CHANGED SINCE LAST BOOT

Memory has been added or removed since the last boot. In EISA mode use Configuration Utility to reconfigure the memory configuration. In ISA mode enter Setup and enter the new memory size in the memory fields.

Memory Verify Error at ...

Indicates an error verifying a value already written to memory. Use the location along with your system's memory map to locate the bad chip.

OFFENDING ADDRESS NOT FOUND

This message is used in conjunction with the I/O CHANNEL CHECK and RAM PARITY ERROR messages when the segment that has caused the problem cannot be isolated.

OFFENDING SEGMENT:

This message is used in conjunction with the I/O CHANNEL CHECK and RAM PARITY ERROR messages when the segment that has caused the problem has been isolated.

PRESS A KEY TO REBOOT

This will be displayed at the bottom screen when an error occurs that requires you to reboot. Press any key and the system will reboot.

PRESS F1 TO DISABLE NMI, F2 TO REBOOT

When BIOS detects a Non-maskable Interrupt condition during boot, this will allow you to disable the NMI and continue to boot, or you can reboot the system with the NMI enabled.

RAM PARITY ERROR - CHECKING FOR SEGMENT ...

Indicates a parity error in Random Access Memory.

Should Be Empty But EISA Board Found PLEASE RUN EISA CONFIGURATION UTILITY

A valid board ID was found in a slot that was configured as having no board ID.

Note:

When this error appears, the system will boot in ISA mode, which allows you to run the EISA Configuration Utility.

**Should Have EISA Board But Not Found
PLEASE RUN EISA CONFIGURATION UTILITY**

The board installed is not responding to the ID request, or no board ID has been found in the indicated slot.

Note:

When this error appears, the system will boot in ISA mode, which allows you to run the EISA Configuration Utility.

Slot Not Empty

Indicates that a slot designated as empty by the EISA Configuration Utility actually contains a board.

Note:

When this error appears, the system will boot in ISA mode, which allows you to run the EISA Configuration Utility.

SYSTEM HALTED, (CTRL-ALT-DEL) TO REBOOT ...

Indicates the present boot attempt has been aborted and the system must be rebooted. Press and hold down the CTRL and ALT keys and press DEL.

**Wrong Board In Slot
PLEASE RUN EISA CONFIGURATION UTILITY**

The board ID does not match the ID stored in the EISA non-volatile memory.

Note:

When this error appears, the system will boot in ISA mode, which allows you to run the EISA Configuration Utility.

FLOPPY DISK(S) fail (80) → Unable to reset floppy subsystem.

FLOPPY DISK(S) fail (40) → Floppy Type mismatch.

Hard Disk(s) fail (80) → HDD reset failed

Hard Disk(s) fail (40) → HDD controller diagnostics failed.

Hard Disk(s) fail (20) → HDD initialization error.

Hard Disk(s) fail (10) → Unable to recalibrate fixed disk.

Hard Disk(s) fail (08) → Sector Verify failed.

Keyboard is locked out - Unlock the key.

Keyboard error or no keyboard present.

Cannot initialize the keyboard. Make sure the keyboard is attached correctly and no keys are being pressed during the boot.

BIOS ROM checksum error - System halted.

The checksum of ROM address F0000H-FFFFFFH is bad.

Memory test fail.

BIOS reports the memory test fail if the onboard memory is tested error.

4.16 BIOS POST Check Point List

AWARD BIOS provides all IBM standard Power On Self Test (POST) routines as well as enhanced AWARD BIOS POST routines. The POST routines support CPU internal diagnostics. The POST checkpoint codes are accessible via the Manufacturing Test Port (I/O port 80h).

Whenever a recoverable error occurs during the POST, the system BIOS will display an error message describing the message and explaining the problem in detail so that the problem can be corrected.

During the POST, the BIOS signals a checkpoint by issuing one code to I/O address 80H. This code can be used to establish how far the BIOS has executed through the power-on sequence and what test is currently being performed. This is done to help troubleshoot faulty system board.

If the BIOS detects a terminal error condition, it will halt the POST process and attempt to display the checkpoint code written to port 80H. If the system hangs before the BIOS detects the terminal error, the value at port 80H will be the last test performed. In this case, the terminal error cannot be displayed on the screen. The following POST checkpoint codes are valid for all AWARD BIOS products with a core BIOS date of 07/15/95 version 6.27 (Enhanced).

Code	Description
CFh	Test CMOS R/W functionality
C0h	Early chipset initialization: - Disable shadow RAM - Disable L2 cache (socket 7 or below) - Program basic chipset registers
C1h	Detect memory - Auto-detection of DRAM size, type and ECC. - Auto-detection of L2 cache (socket 7 or below)
C3h	Expand compressed BIOS code to DRAM
C5h	Call chipset hook to copy BIOS back to E000 & F000 shadow RAM.
0h1	Expand the Xgroup codes locating in physical address 1000:0
02h	Reserved
03h	Initial Superio_Early_Init switch
04h	Reserved
05h	1. Blank out screen 2. Clear CMOS error flag
06h	Reserved
07h	1. Clear 8042 interface 2. Initialize 8042 self-test
08h	1. Test special keyboard controller for Winbond 977 series Super I/O chips 2. Enable keyboard interface
09h	Reserved
0Ah	Disable PS/2 mouse interface (optional). Auto detect ports for keyboard & mouse followed by a port & interface swap (optional). Reset keyboard for Winbond 977 series Super I/O chips.
0Bh	Reserved
0Ch	Reserved
0Dh	Reserved
0Eh	Test F000h segment shadow to see whether it is R/W-able or not. If test fails, keep beeping the speaker.
0Fh	Reserved
10h	Auto detect flash type to load appropriate flash R/W codes into the run time area in F000 for ESCD & DMI support.
11h	Reserved
12h	Use walking 1's algorithm to check out interface in CMOS circuitry. Also set real-time clock power status, and then check for override.
13h	Reserved
14h	Program chipset default values into chipset. Chipset default values are MODBINable by OEM customers.
15h	Reeserved
16h	Initial Early_Init_Onboard_Generator switch

17h	Reserved
18h	Detect CPU information including brand, SMI type (Cyrrix or Intel) and CPU level (586 or 686).
19h	Reserved
1Ah	Reserved
1Bh	Initial interrupts vector table. If no special specified, all H/W interrupts are directed to SPURIOUS_INT_HDLR & S/W interrupts to SPURIOUS_soft_HDLR.
1Ch	Reserved
1Dh	Initial EARLY_PM_INIT switch
1Eh	Reserved
1Fh	Load keyboard matrix (notebook platform)
20h	Reserved
21h	HPM initialization (notebook platform)
22h	Reserved
23h	<ol style="list-style-type: none"> 1. Check validity of RTC value: e.g. a value of 5Ah is an invalid value for RTC minute. 2. Load CMOS settings into BIOS stack. If CMOS checksum fails, use default value instead. 3. Prepare BIOS resource map for PCI & PnP use. If ESCD is valid, take into consideration of the ESCD's legacy information. 4. Onboard clock generator initialization. Disable respective clock resource to empty PCI & DIMM slots. 5. Early PCI initialization: <ul style="list-style-type: none"> - Enumerate PCI bus number - Assign memory & I/O resource - Search for a valid VGA device & VGA BIOS, and put it into C000:0.
24h	Reserved
25h	Reserved
26h	Reserved
27h	Initialize INT 09 buffer
28h	Reserved
29h	Program CPU internal MTRR (P6 & PII) for 0-640K memory address. Initialize the APIC for Pentium class CPU. Program early chipset according to CMOS setup. Example: onboard IDE controller. Measure CPU speed. Invoke video BIOS.
2Ah	Reserved
2Bh	Reserved
2Ch	Reserved
2Dh	Initialize multi-language. Put information on screen display, including Award title, CPU type, CPU speed
2Eh	Reserved
2Fh	Reserved
30h	Reserved
31h	Reserved

32h	Reserved
33h	Reset keyboard except Winbond 977 series Super I/O chips
34h	Reserved
35h	Reserved
36h	Reserved
37h	Reserved
38h	Reserved
39h	Reserved
3Ah	Reserved
3Bh	Reserved
3Ch	Test 8254
3Dh	Reserved
3Eh	Test 8259 interrupt mask bits for channel 1
3Fh	Reserved
40h	Test 8259 interrupt mask bits for channel 2
41h	Reserved
42h	Reserved
43h	Test 8259 functionality
44h	Reserved
45h	Reserved
46h	Reserved
47h	Initialize EISA slot
48h	Reserved
49h	Calculate total memory by testing the last double word of each 64K page
4Ah	Reserved
4Bh	Reserved
4Ch	Reserved
4Dh	Reserved
4Eh	<ol style="list-style-type: none"> 1. Initialize L2 cache for P6 class CPU & program CPU with proper cacheable range 2. Initialize the APIC for P6 class CPU 3. On MP platform, adjust the cacheable range to smaller one in case the cache able ranges between each CPU are not identical
4Fh	Reserved
50h	Initialize USB
51h	Reserved
52h	Test all memory (clear all extended memory to 0)
53h	Reserved
54h	Reserved
55h	Display number of processors (multi-processor platform)
56h	Reserved
57h	<ol style="list-style-type: none"> 1. Display PnP logo 2. Early ISA PnP initialization <ul style="list-style-type: none"> - Assign CSN to every ISA PnP device

58h	Reserved
59h	Initialize the combined Trend Anti-Virus code
5Ah	Reserved
5Bh	(Optional Feature) Show message for entering AWDFLASH.EXE from FDD (optional)
5Ch	Reserved
5Dh	1. Initialize Init_Onboard_Super_IO switch 2. Initialize Init_Onboard_AUDIO switch
5Eh	Reserved
5Fh	Reserved
60h	Okay to enter Setup utility; i.e. not until this POST stage can users enter the CMOS setup utility.
61h	Reserved
62h	Reserved
63h	Reserved
64h	Reserved
65h	Initialize PS/2 Mouse
66h	Reserved
67h	Prepare memory size information for function call: INT 15h ax=E820h
68h	Reserved
69h	Turn on L2 cache
6Ah	Reserved
6Bh	Program chipset registers according to items described in Setup & Auto-configuration table.
6Ch	Reserved
6Dh	1. Assign resources to all ISA PnP devices. 2. Auto assign ports to onboard COM ports if the corresponding item in Setup is set to "AUTO".
6Eh	Reserved
6Fh	1. Initialize floppy controller 2. Set up floppy related fields in 40:hardware
70h	Reserved
71h	Reserved
72h	Reserved
73h	(Optional Feature) Enter AWDFLASH.EXE if : - AWDFLASH is found in floppy drive. - ALT+F2 is pressed
74h	Reserved
75h	Detect & install all IDE devices: HDD, LS120, ZIP, CDROM.....
76h	Reserved
77h	Detect serial ports & parallel ports
78h	Reserved
79h	Reserved
7Ah	Detect & install co-processor

7Bh	Reserved
7Ch	Reserved
7Dh	Reserved
7Eh	Reserved
7Fh	Switch back to text mode if full screen logo is supported - If errors occur, report errors & wait for keys - If no errors occur or F1 key is pressed to continue: . Clear EPA or customization logo
80h	Reserved
81h	Reserved
82h	1. Call chipset power management hook 2. Recover the text font used by EPA logo (not for full screen logo) 3. If password is set, ask for password
83h	Save all data in stack back to CMOS
84h	Initialize ISA PnP boot devices
85h	1. USB final Initialization 2. NET PC: Build SYSID structure 3. Switch screen back to text mode 4. Set up ACPI table at top of memory 5. Invoke ISA adapter ROMs 6. Assign IRQs to PCI devices 7. Initialize APM 8. Clear noise of IRQs
86h	Reserved
87h	Reserved
88h	Reserved
89h	Reserved
90h	Reserved
91h	Reserved
92h	Reserved
93h	Read HDD boot sector information for Trend Anti-Virus code
94h	1. Enable L2 cache 2. Program boot up speed 3. Chipset final initialization 4. Power management final initialization 5. Clear screen & display summary table 6. Program K6 write allocation 7. Program P6 class write combining
95h	1. Program daylight saving 2. Update keyboard LED & typematic rate
96h	1. Build MP table 2. Build & update ESCD 3. Set CMOS century to 20h or 19h 4. Load CMOS time into DOS timer tick 5. Build MSIRQ routing table
FFh	Boot attempt (INT 19h)

4.17 BIOS Flash Utility

Utilize AWARD Flash BIOS programming utility to update on-board BIOS for the future new BIOS version. Please contact your technical window to get this utility if necessary.

Note:

Remark or delete any installed Memory Management Utility (such as HIMEM.SYS, EMM386.EXE, QEMM.EXE, ..., etc.) in the CONFIG.SYS files before running Flash programming utility.

Chapter 5

Troubleshooting

This chapter provides you a few useful tips to quickly get your ROBO-8820VG2/VF2 running with no failure. As basic hardware installation has been addressed in Chapter 3, this chapter will basically focus on system integration issues, in terms of backplane setup, BIOS setting, and OS diagnostics.

5.1 Backplane Setup

Backplane

ROBO-8820VG2/VF2 is a full-sized SHB with newly design of PICMG 64 bit PCI-X architecture, which runs at speeds up to 133 MHz. Therefore, ROBO-8820VG2/VF2 is only able to run on PICMG 64 bit PCI/PCI-X Backplane.

The PCI specification allows for three different PCI add-on cards: 3.3V, 5V and "Universal" adapters, but only 3.3V signaling is allowed for 66MHz or greater operations per specification. New PCI controllers are manufactured to operate at 3.3V, while older options were 5V.

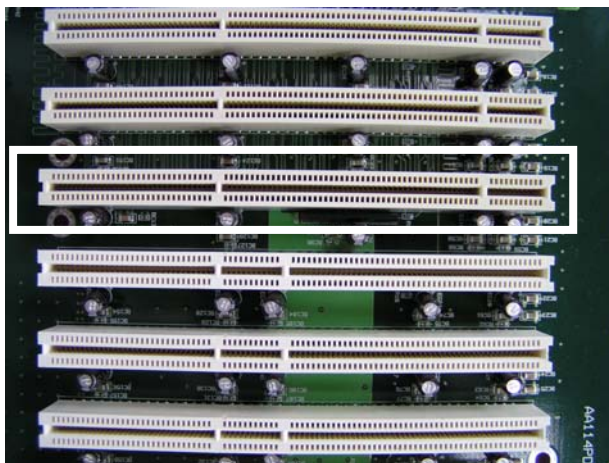
Our Backplane had the newly designed 3.3V, 64 bit PCI slots, which support PCI / PCI-X architecture. Also, we had design the 5V, 64 bit PCI slots, which are keying to support both of 64 bit and 32 bit PCI devices.

PCI Slots Specification

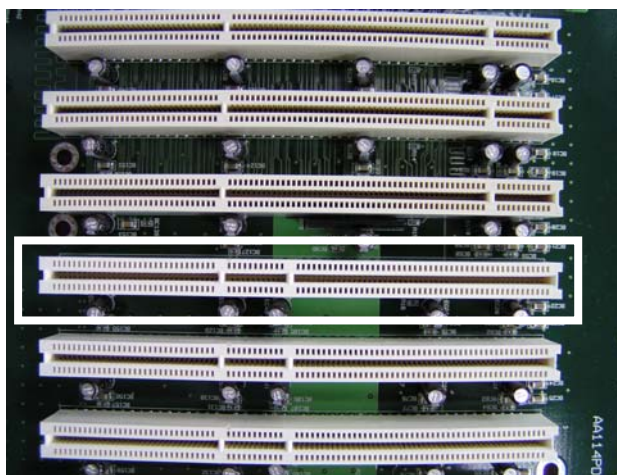
Please check the specification of the PCI devices before using any of them. Please be sure about the specification of the PCI Device could meet our design of PCI/ PCI-X architecture for ROBO-8820VG2/VF2.

The Pin Definition (Golden Fingers) of the PCI device had differences between the 3.3V, 64bit PCI device and 5V, 64bit PCI device. The below picture shows the differences between them:

The 3.3V, 64 bit PCI slots



The 5V, 64 bit PCI Slot



The Below chart shows the specification for the design of system Bus:

Bus Width	Bus Frequency	Bus Bandwidth	PCI Slots	PCI-X Slots
32 bit	33 MHz (5V, 3.3V,	133 MB/Sec	4	N/A
64 bit	33 MHz (5V, 3.3V,	133 MB/Sec	4	N/A
64 bit	66 MHz (3.3V, Universal)	533 MB/Sec	2	4
64 bit	100 MHz (3.3V, Universal)	800 MB/Sec	N/A	2
64 bit	133 MHz (3.3V, Universal)	1.066 GB/Sec	N/A	1

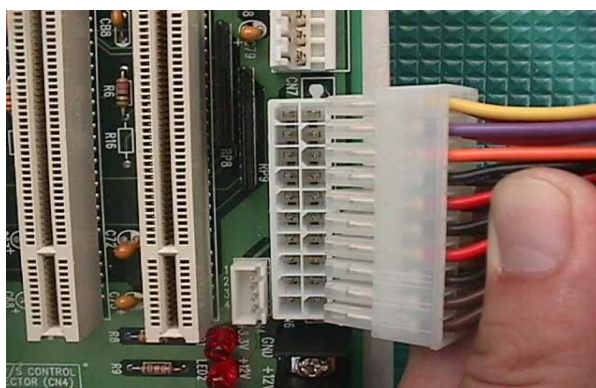
P4 Power connector

ROBO-8820VG2/VF2 requires power drawing from the 12V connector. The CPU supplementary power connector (ATX1, ATX2) should be connected at all time for this P4 system to run properly. If the system's main power comes from a backplane, the CPU supplementary power connector (ATX1, ATX2) should still be connected.

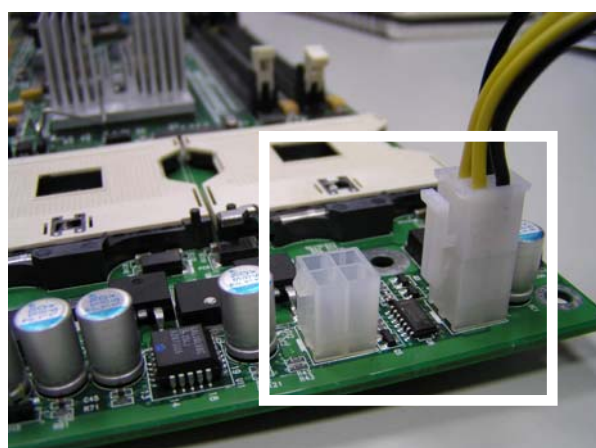
ATX power

ROBO-8820VG2/VF2 is designed to also support ATX mode. Please refer to the following instruction to apply ATX power on your ROBO-8820VG2/VF2 and backplane.

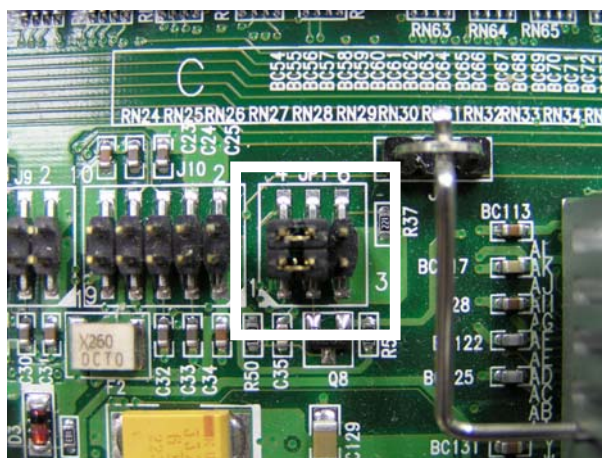
Step1: Connect 20-pin power cable of the ATX POWER with ATX POWER CONNECTOR (20-pin) on the backplane



Step2: Connect the 12V power connector (4 pin) to ATX1, and ATX2.

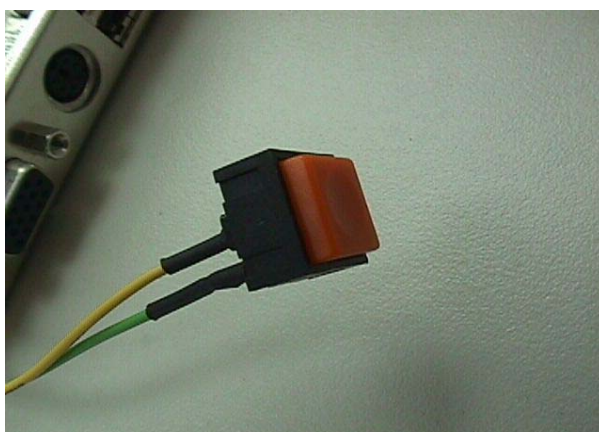


Step3: Check the jumper setting of the JP1, the default setting will short the 1-2 pin for ATX Mode.



Step4: Connect TOGGLE SWITCH with J1 connector (2 pin) on the Backplane. The system power of the ROBO-8820VG2/VF2 controlled by the TOGGLE SWITCH, which is connect on the Backplane.

Step5: The figure below is the TOGGLE SWITCH, which is used to switch the ATX Power on/off for SHB. Usually the TOGGLE SWITCH is located on the chassis front panel. Pressing the switch button once will turn power on, and press again to turn it off.



Q: In addition to the above description, is there anything to do to finish up an ATX system?

A: Yes. ROBO-8820VG2/VF2 needs to be configured to support ATX function for the above cabling.

Q: How can I build up an AT system using ATX power supply?

A: Short the JP1 Jumper of pin 2, and pin 3 on the ROBO-8820VG2/VF2 to set the AT mode. ROBO-8820VG2/VF2 can stimulate AT Mode.

If the ATX power supply has a switch, such as ORION-300ATX, and use the power supply switch as the system power on switch when using the AT Mode.

In all cases when using the ATX Mode, users need apply a 2-pin AT (on/off) TOGGLE SWITCH connect on the backplane J1 connector of step 4. However, power supply switch needs to be moved to “on”, if there is one.

5.2 Onboard hardware installation

For ROBO-8820VG2/VF2, there is one PA-I1KUC adapter board with bracket. The Extensive Daughter Board had 2 USB connectors, 1 PS2 Keyboard/ Mouse connector, and 1 COM port connector. The adapter cable for PA-I1KUC without Fool-proofing, please check and connect the cable correctly.

The below picture shows the PA-I1KUC adapter board; from left to right, 1 COM port connector, 1 PS2 Keyboard/ Mouse connector, and 2 USB connectors.



Q: How do I connect my keyboard and mouse?

A: Users may always adopt PS/2 keyboard and mouse over the PS/2 interface (through Y-cable), on the Extensive Daughter Board (PA-I1KUC adapter board) of ROBO-8820VG2/VF2. If without using Y-cable, the default setting of the PS/2 connector is for Keyboard usage.



Q: OK. I have finished up hardware installation, but I got nothing when I power on the system. Why?

A: Couple points may be checked for correcting power-on failure.

1. Check ROBO-8820VG2/VF2 jumper, JP1. For ATX power supply used for AT mode, JP1 needs to be set at 2-3. Otherwise, it needs to be set at 1-2. Incorrect power setting will not allow you to power on the system.
2. Double check if every connector is attached with the correct cable.
3. If you have changed processor with different system clock, please move jumper of JP1 (Also be the CMOS clear Jumper) to 5-6, power on the system to clear CMOS (move on/off switch from off to on for AT mode, or toggle the switch for ATX mode), power off the system, move JP1 back to 4-5, and power on again.

Q: I power on the system, but the CPU speed is not correct. Why?

A: If you have ever loaded the BIOS optimal default, thank you for doing so. However, this will force the BIOS to pick up the default CPU core/bus ratio as well. It needs to be emphasized again that ROBO-8820VG2/VF2 does not have switch or jumper to configure CPU core/bus ratio. This is done through BIOS automatically. Please check in the “Frequency/Voltage Control” section of Chapter 4 to adjust this clock/bus ratio. System default setting is automatically setting for safety CPU Clock Ratio, which should be “MIN = 16x”. When you plug in the Xeon processors from Intel and you will need to set the CPU Clock Ratio in the BIOS setting.

Q: I connect two IDE devices over one IDE flat cable, but the system either does not start, or just hangs from time to time. Why?

A: Please make sure that you have configured the two IDE devices as a master device and a slave device, respectively.

5.3 BIOS Setting

It is assumed that users have correctly adopted modules and connected all the device cables required before turning on AT power. CPU, CPU fan, CPU fan power cable, 184-pin DDR SDRAM, keyboard, mouse, floppy drive, IDE hard disk, printer, VGA connector, device power cables, ATX accessories or 12V 4-pin power cable are good examples that deserve attention. With no assurance of properly and correctly accommodating these modules and devices, it is very possible to encounter system failures that result in malfunction of any device.

To make sure that a successful initialization with ROBO-8820VG2/VF2, it is recommended, when going with the boot-up sequence, to hit “DEL” key and enter the BIOS setup menu and perform following operations:.

Loading the default optimal setting

When prompted with the main setup menu, please scroll down to “**Load Optimal Defaults**”, press “Enter” and “Y” to load in default optimal BIOS setup. This will force your BIOS setting back to the initial factory configuration. It is recommended to do this so you can be sure the system is running with the BIOS setting that Portwell has highly endorsed. As a matter of fact, users can load the default BIOS setting any time when system appears to be unstable in boot up sequence.

Auto Detect Hard Disks

In the BIOS => Standard CMOS setup menu, pick up any one from Primary/Secondary Master/Slave IDE ports, and press the “Enter” key. Setup the selected IDE port and its access mode to “Auto”. This will force system to automatically pick up the IDE devices that are being connected each time system boots up.

Improper disable operation

There are too many occasions where users disable a certain device/feature in one application through BIOS setting. These variables may not be set back to the original values when needed. These devices/features will certainly fail to be detected.

When the above conditions happen, it is strongly recommended to check the BIOS settings. Make sure certain items are set as they should be. These include the floppy drive, COM1/COM2 ports, parallel port, USB ports, external cache, on-board VGA and Ethernet.

It is also very common that users would like to disable a certain device/port to release IRQ resource. A few good examples are

- disable COM1 serial port to release IRQ #4
- disable COM2 serial port to release IRQ #3
- disable parallel port to release IRQ #7
- disable PS/2 mouse to release IRQ #12,
- ..., etc.

A quick review of the basic IRQ mapping is given below at the Chapter 6, Appendix 6.4 Interrupt Request Line (IRQ), which for your reference.

It is then very easy to find out which IRQ resource is ready for additional peripherals. If IRQ resource is not enough, please disable some devices listed above to release further IRQ numbers.

5.4 OS Diagnostics

What will be presented here is a brief guide to properly house-in the driver for any Microsoft Windows-95/98/NT device. For other operating systems, please refer to OS manual/guidebook.

Booting

Users may find quite a lot of Windows-95/98 hang during loading sequence. Windows logo stays with no progress, or simply no display is given. Please restart the system and hit "F5" when loading the Windows system and enter "Safe mode". Users will always be allowed to enter "Safe mode" with success to remove devices that are not properly running or installed. Please proceed to do so and restart the Windows. Devices with removed drivers will be automatically detected again. The drivers will be loaded automatically, with drivers have been included in the system database.

For Windows-NT 4.0 users, it is always not recommended to change hardware configuration after the first installation. However, if such a change is needed, please note that sometimes Windows-NT 4.0 will stop loading and prompt error messages on a blue screen. Please note that reinstallation of this NT hard disk may be required and backup is highly recommended. If this NT hard disk is installed with FAT16 disk format, please boot up your system with any Windows OS. Data will be retrievable from this hard disk. If this is a NT hard disk with NTFS, data can only be retrieved from a NTFS OS.

Display setup

By default, any Windows OS starts with 640 x 480 with 16 colors display. The display driver provided in ROBO-8820VG2/VF2 product CDROM Disc can be installed into Operating System to maximize the VGA performance. If the monitor used can not be identified by Microsoft® Windows, user may need to set in the display from the setup menu, a system monitor to correctly retrieve display output. For Windows-NT 4.0 users, ROBO-8820VG2/VF2 provides AGP on-board display feature, Service Pack 3.0 or above is required to activate this display feature.

Network setup

Windows-95/98 users.

1. Please apply a PCI network card over PCI slot, or simply use the on-board Fast Ethernet device.
2. Start Windows-95/98 and let Window-95/98 automatically detect your network adapter.
3. Provide the driver and complete installation.
4. Restart windows system is required.
5. Upon reloading windows, please go to Control Panel -> System -> Device Manager and check if network adapter has been properly installed. A warning sign will be prompted if the network adaptor is not properly installed.
6. Please remove this network device from system setup menu and restart windows to re-detect your network adapter again.
7. After the hardware installation is completed, please go to Control Panel -> Network to set up your networking configuration. This includes DNS, IP, and Gateway. Appropriate protocols are required to carry your networking activities. Please contract local network administrator for additional assistance.

For Windows-NT 4.0 users:

1. Please install your network adapter manually in Control Panel -> Network -> Adapter. Drivers are required at this stage.
2. Proceed "Binding" after you loading of the driver.
3. Change to Protocol label and load in the protocols that you are interested (generally, TCP/IP). Configuring IP, gateway and DNS is required for TCP/IP protocol.
4. Proceed again "Binding" after complete the protocol loading.
5. Restart system.
6. There is also situation that the installed network adapter is not functional anymore or old network driver stays in the system after network device had changed. Please remove all the network adapters and protocols from network setup menu and redo the loading of driver and protocols again.
7. Network setup within Windows-NT 4.0 may require in-depth knowledge of Windows network environment.

Note:

Please check the Drivers CDROM Disc or visit our technical web site at:

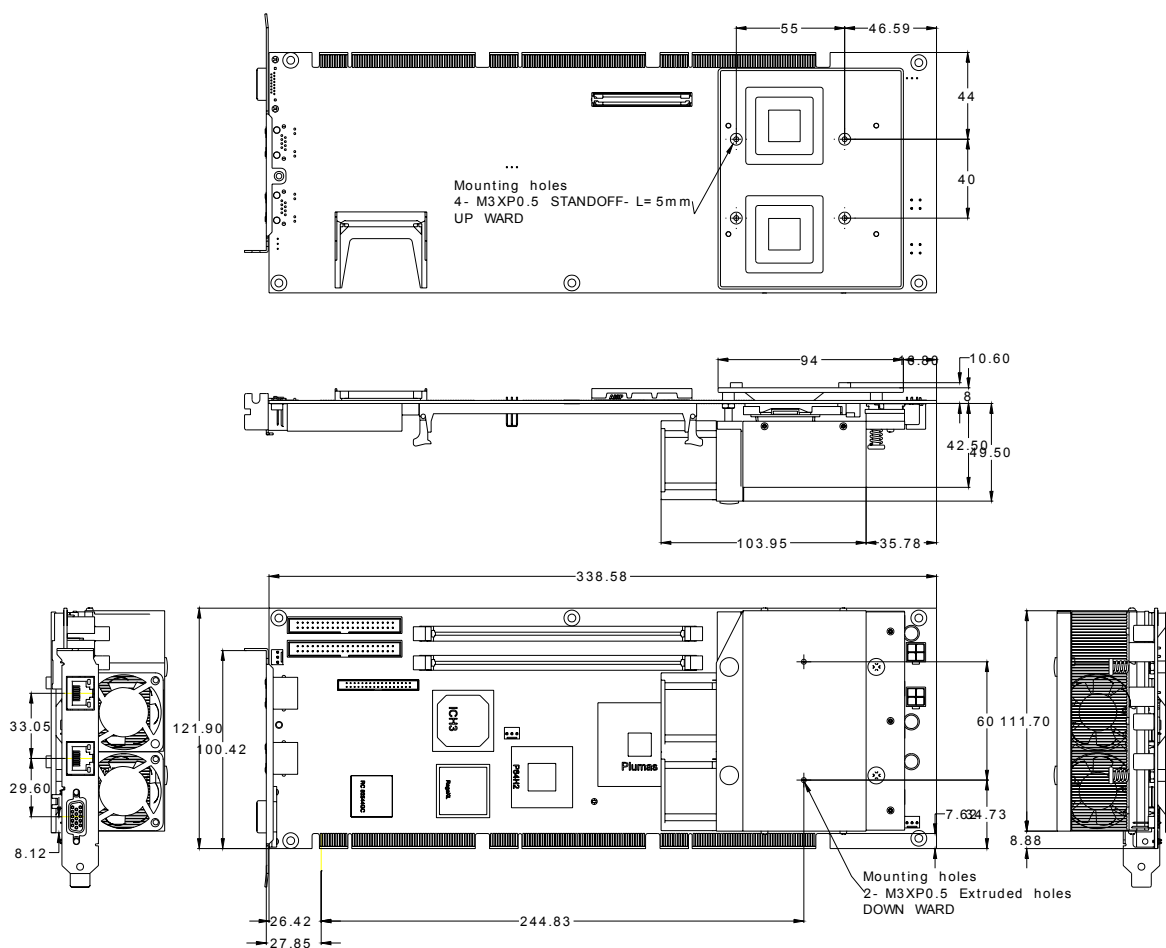
<http://www.portwell.com.tw>

For all other OS, additional technical information, and latest updates.

Chapter 6 Appendix

Useful information is provided in this chapter. That includes mechanical drawing of ROBO-8820VG2 series with proprietary CPU cooler, examples of enhanced fixation for CPU cooler, I/O port address map and interrupt request lines (IRQs).

6.1 Mechanical Dimension with CPU Cooler



6.2 System Memory Address Map

Each On-board device in the system is assigned a set of memory addresses, which also can be identical of the device. The following table lists the system memory address used.

Memory Area	Size	Device Description
0000 - 003F	1K	Interrupt Area
0040 - 004F	0.3K	BIOS Data Area
0050 - 006F	0.5K	System Data
0070 - 0629	22K	DOS
062A - 0E01	31K	Program Area
0E02 - 9FFF	583K	[Available]
= Conventional memory ends at 640K =		
A000 - AFFF	64K	VGA Graphics
B000 - B7FF	32K	Unused
B800 - BFFF	32K	VGA Text
C000 - C7FF	32K	Video ROM
C800 - CFFF	32K	ROM
D000 - DFFF	64K	Page Frame
E000 - EFFF	64K	Unused
F000 - FFFF	64K	System ROM
HMA	64K	First 64K Extended

6.3 Interrupt Request Lines (IRQ)

Peripheral devices can use interrupt request lines to notify CPU for the service required. The following table shows the IRQ used by the devices on board.

IRQ#	Current Use	Default Use
IRQ 0	SMARTDRV	System Timer
IRQ 1	SMARTDRV	Keyboard Event
IRQ 2	[Unassigned]	Usable IRQ
IRQ 3	System ROM	COM 2
IRQ 4	System ROM	COM 1
IRQ 5	[Unassigned]	Usable IRQ
IRQ 6	System ROM	Diskette Event
IRQ 7	[Unassigned]	Usable IRQ
IRQ 8	System ROM	Real-Time Clock
IRQ 9	[Unassigned]	Usable IRQ
IRQ 10	[Unassigned]	Usable IRQ
IRQ 11	[Unassigned]	Usable IRQ
IRQ 12	System ROM	IBM Mouse Event
IRQ 13	System ROM	Coprocessor Error
IRQ 14	System ROM	Hard Disk Event
IRQ 15	[Unassigned]	Usable IRQ